

Visual Prompting

Hyojin Bahng and Phillip Isola, MIT

CVPR 2023 Tutorial on Prompting in Vision
June 19, 2023

Overview

1. What is visual prompting?
2. Promptable vision foundation models
3. Visual prompt learning

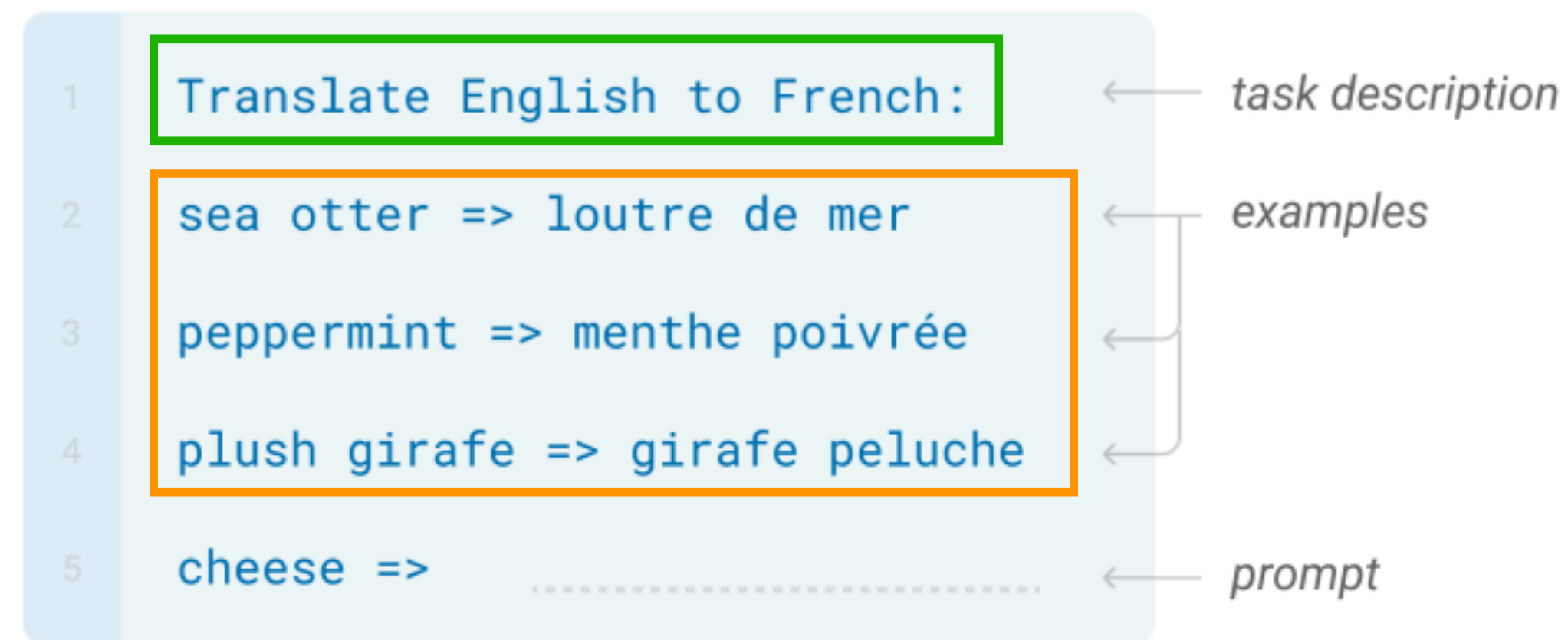
What is Visual Prompting?

Language Prompting

- Steer the behavior of language models for desired outcomes *without* updating the model weights

Few-shot

In addition to the task description, the model sees a few examples of the task. No gradient updates are performed.

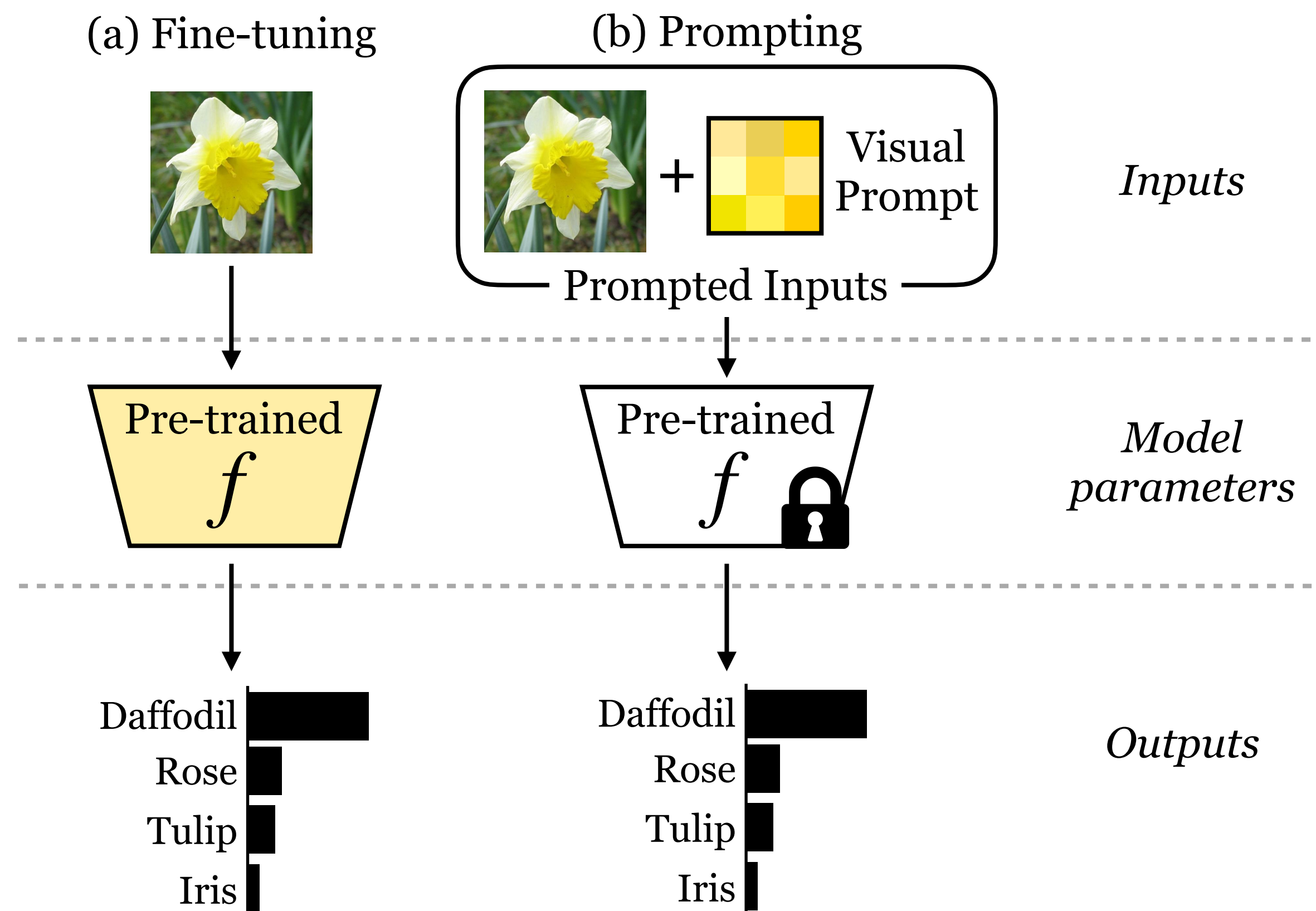


Natural language task description + examples as demonstrations

(No model update!!)

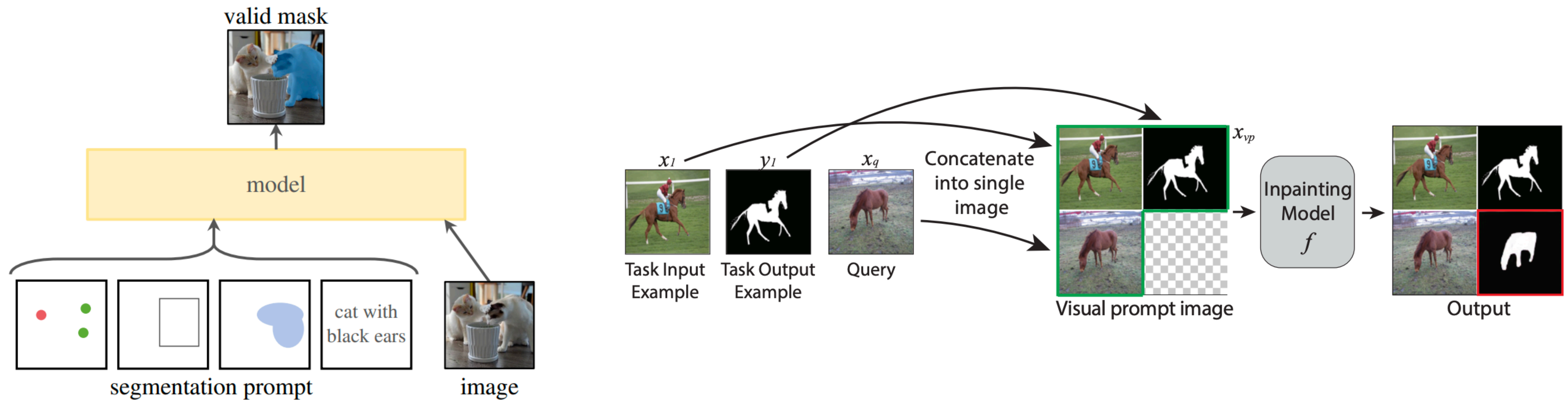
Visual Prompting

- Visual input that helps the model predict the desired answer *without* updating model weights



Visual Prompting

- Points, boxes, masks, input-output image examples



Why is it interesting to adapt a model in input space?

Human-compatibility

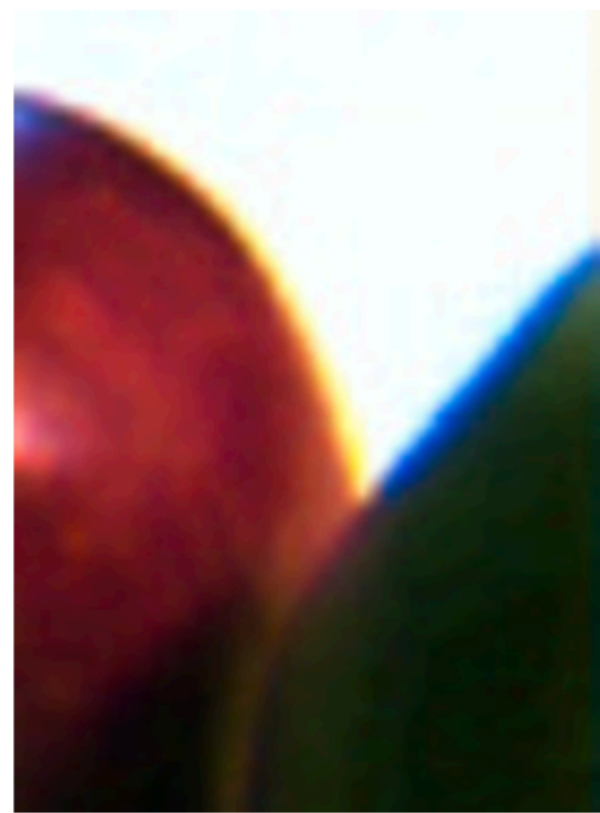
- Inputs are usually human interpretable.
 - End users can intervene on inputs.
- > Prompting is an interface to model editing that everyone can use!

History: User interaction to steer models

Image Analogies

Aaron Hertzmann^{1,2} *Charles E. Jacobs*² *Nuria Oliver*² *Brian Curless*³ *David H. Salesin*^{2,3}

¹New York University ²Microsoft Research ³University of Washington



A



A'

⋮

⋮



B



B'

⋮



Prompt



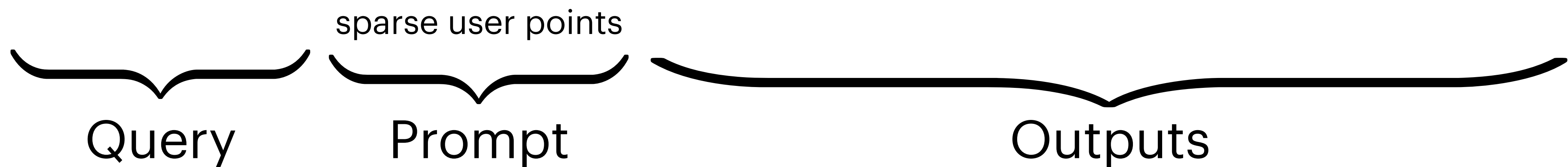
Query



Prediction

History: User Interaction with Deep Networks

- Build the model to obey given control parameters
- e.g. Interactive colorization



So what's new about prompting?

Conditional models are *trained* to respond to seen controls

Prompting is about *adapting* models to do *things they were not explicitly trained to do* (*adapt to unseen distributions and tasks*)

Which could be by finding the best ways to make use of the “input controls” of a conditional model

Why is it interesting to adapt a model in input space?

Flexible integration with other systems

- A promptable model can perform a new task at inference time by acting as a *component* in a larger system

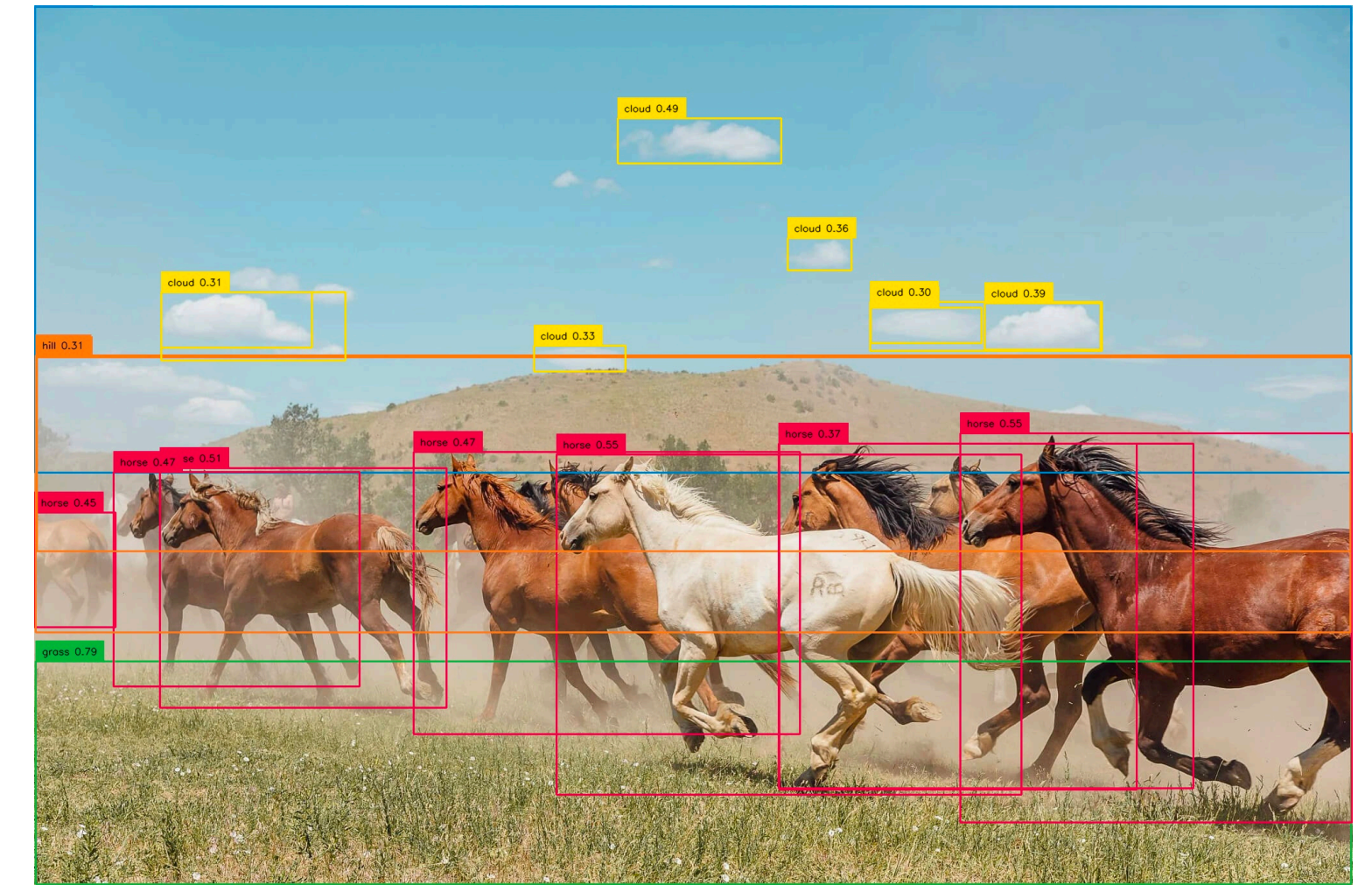
Input Image



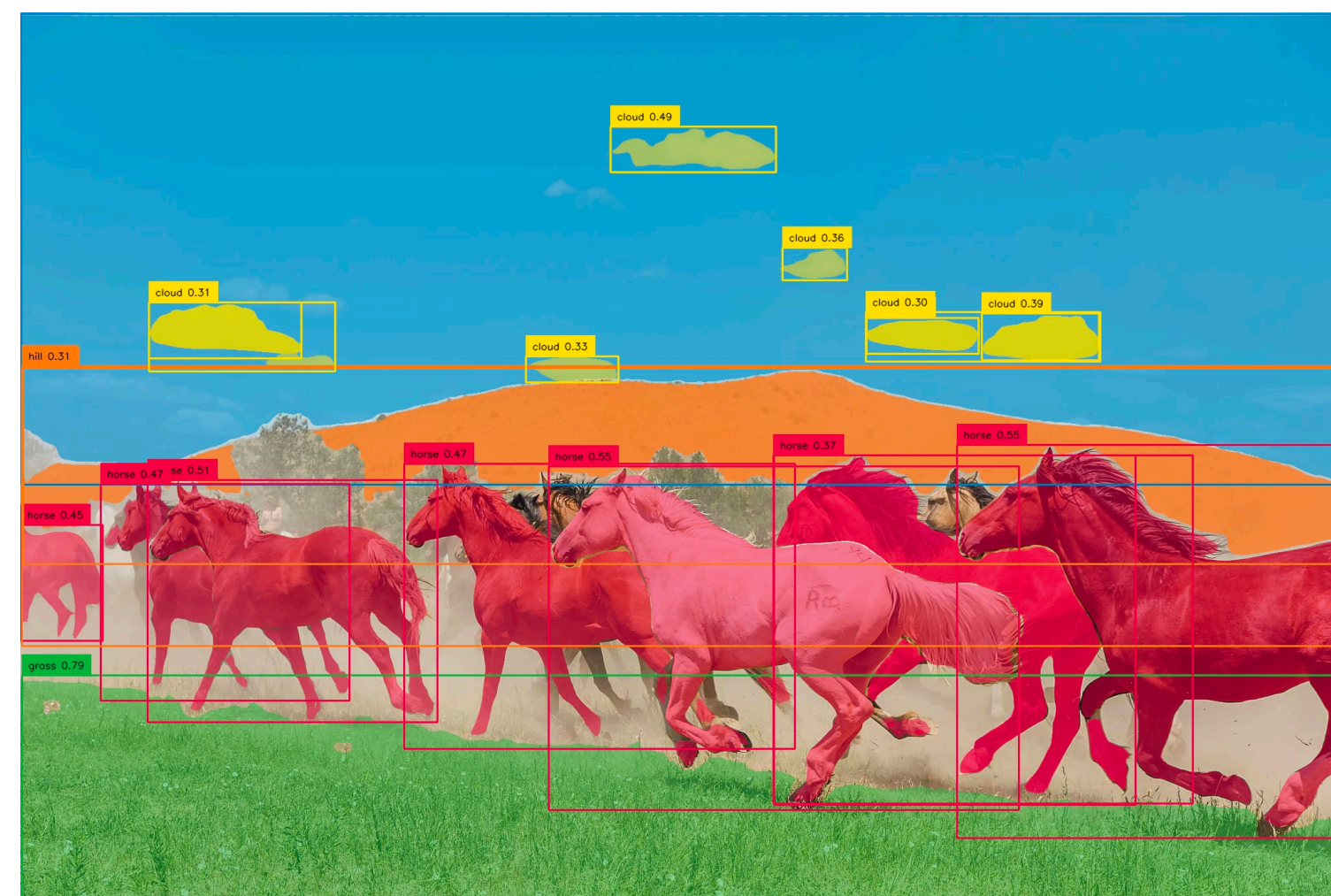
Object
Detector

e.g. GroundingDINO

Predicted Boxes



Predicted Masks



Predicted boxes
as **visual prompt**

Promptable
Segmentation
Model

e.g. Segment Anything

Input Image



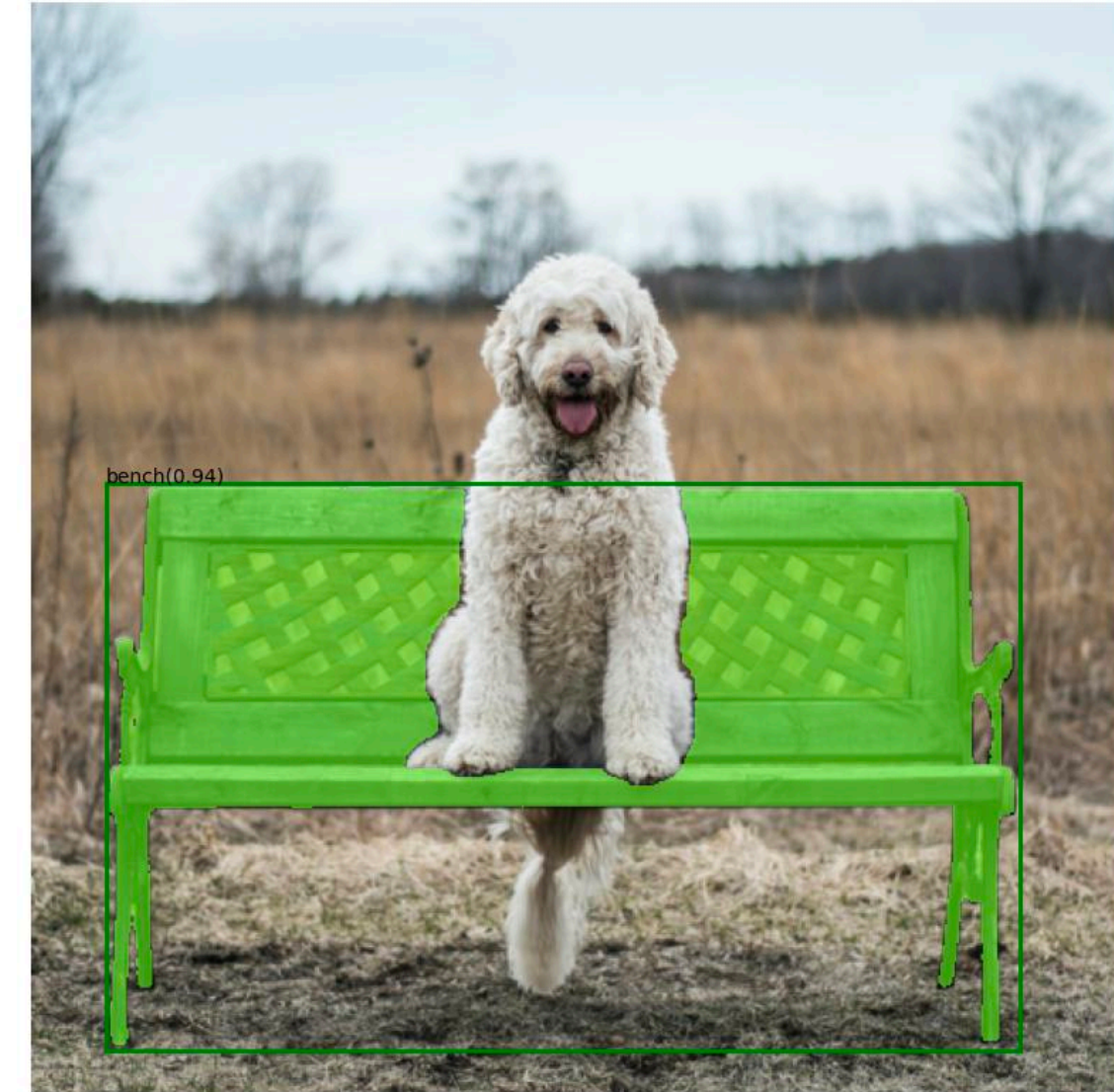
Prompt:
"bench"

Grounding
DINO

Predicted boxes
as **visual prompt**

Segment
Anything

Annotated Image



Inpaint Image



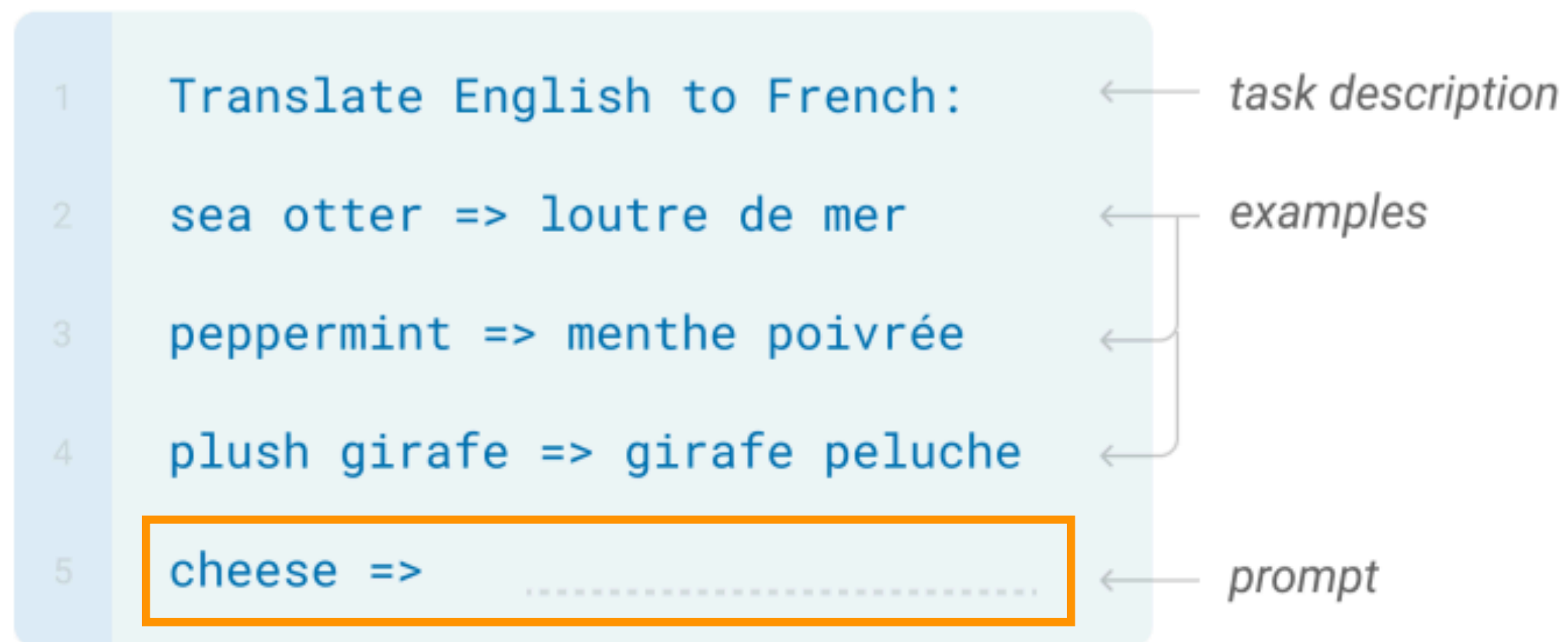
Prompt:
"A sofa, high
quality, detailed"

Stable
Diffusion

Promptable Vision Foundation Models

How do we obtain models that allow visual prompting at inference time?

Language



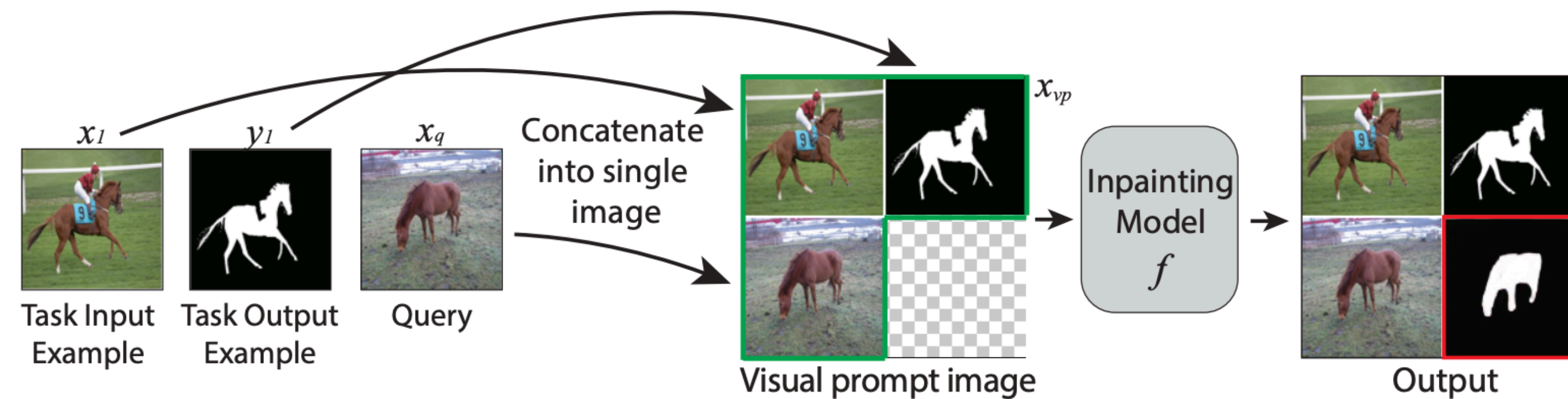
Reformulates input as a language modeling task

Vision

- Image In-painting
- Image Segmentation
- Image Generation

Visual Prompting via Image Inpainting

- Can we have a single general model that can perform a wide range of tasks *without any fine-tuning*?

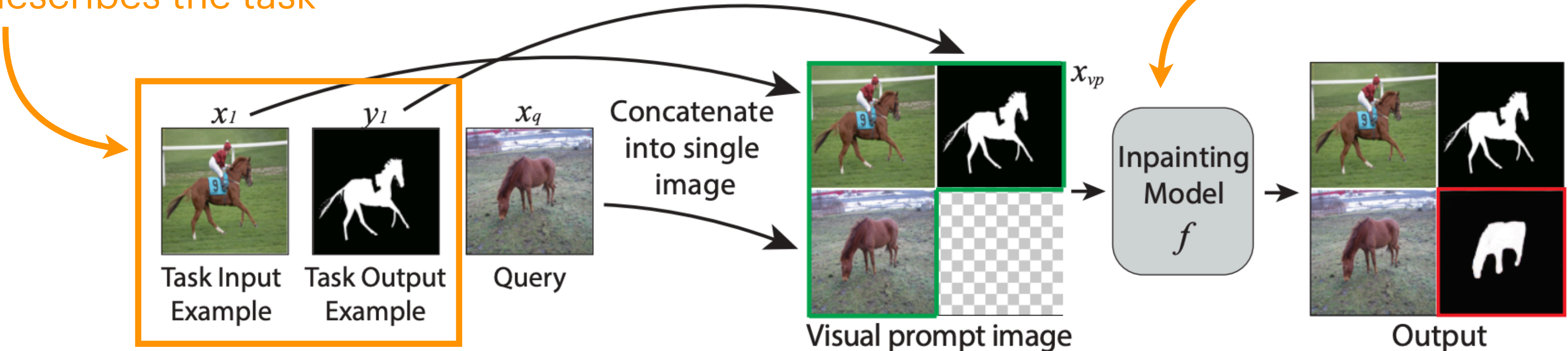


Visual Prompting via Image Inpainting

- Poses vision tasks as simple image in-painting!

Input-output image examples as demonstration = describes the task

Goal: Predict the masked region to be consistent with given examples



Different in-context examples → different vision tasks!

Visual Prompting via Image Inpainting

Training Set

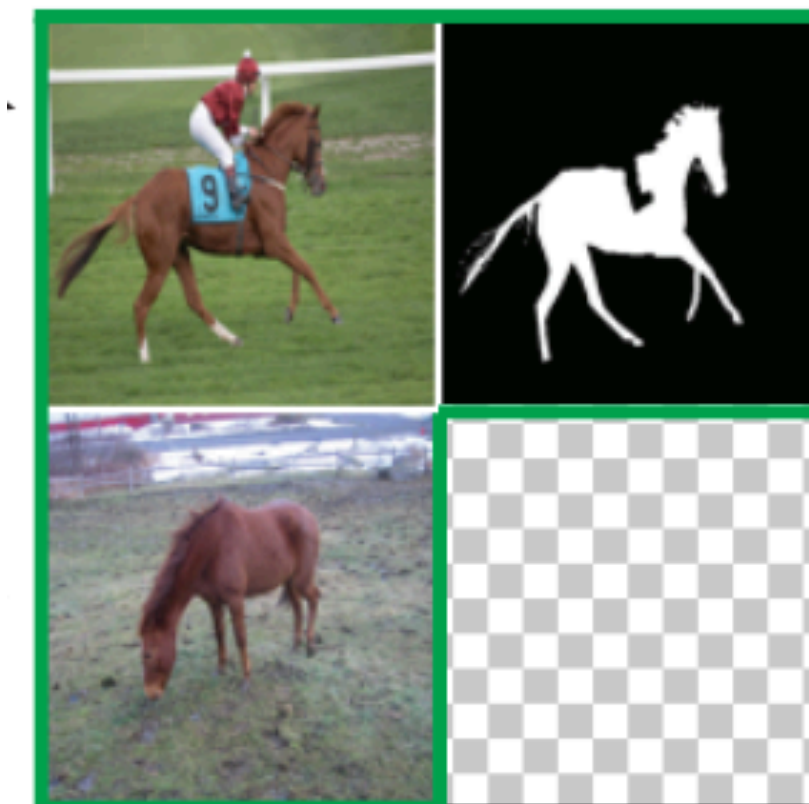


Natural Images

Domain gap



Visual Prompt
at Inference

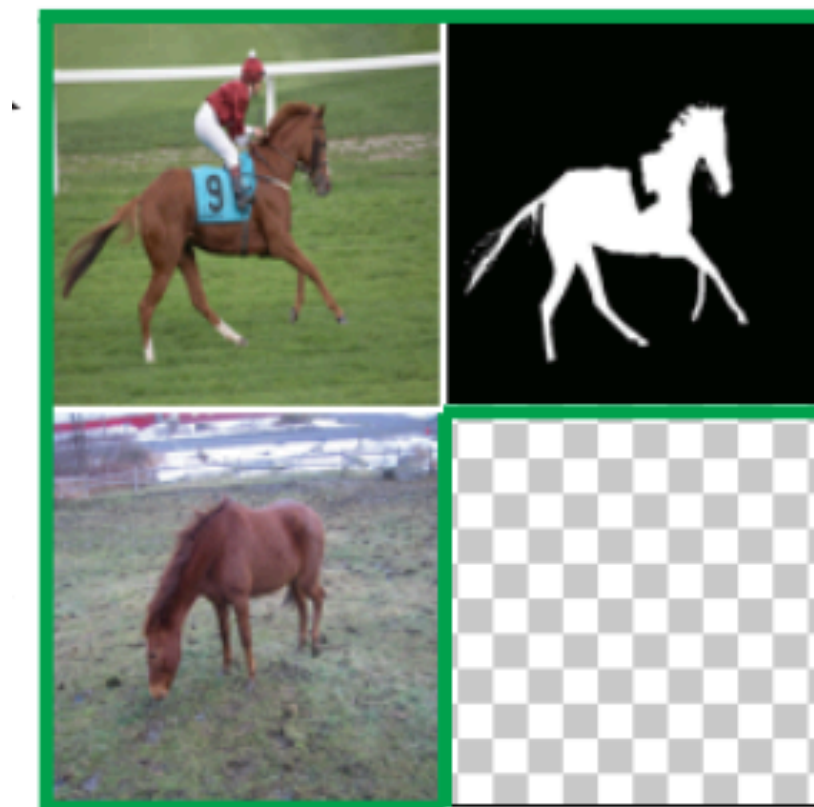


Visual Prompting via Image Inpainting

Training Set



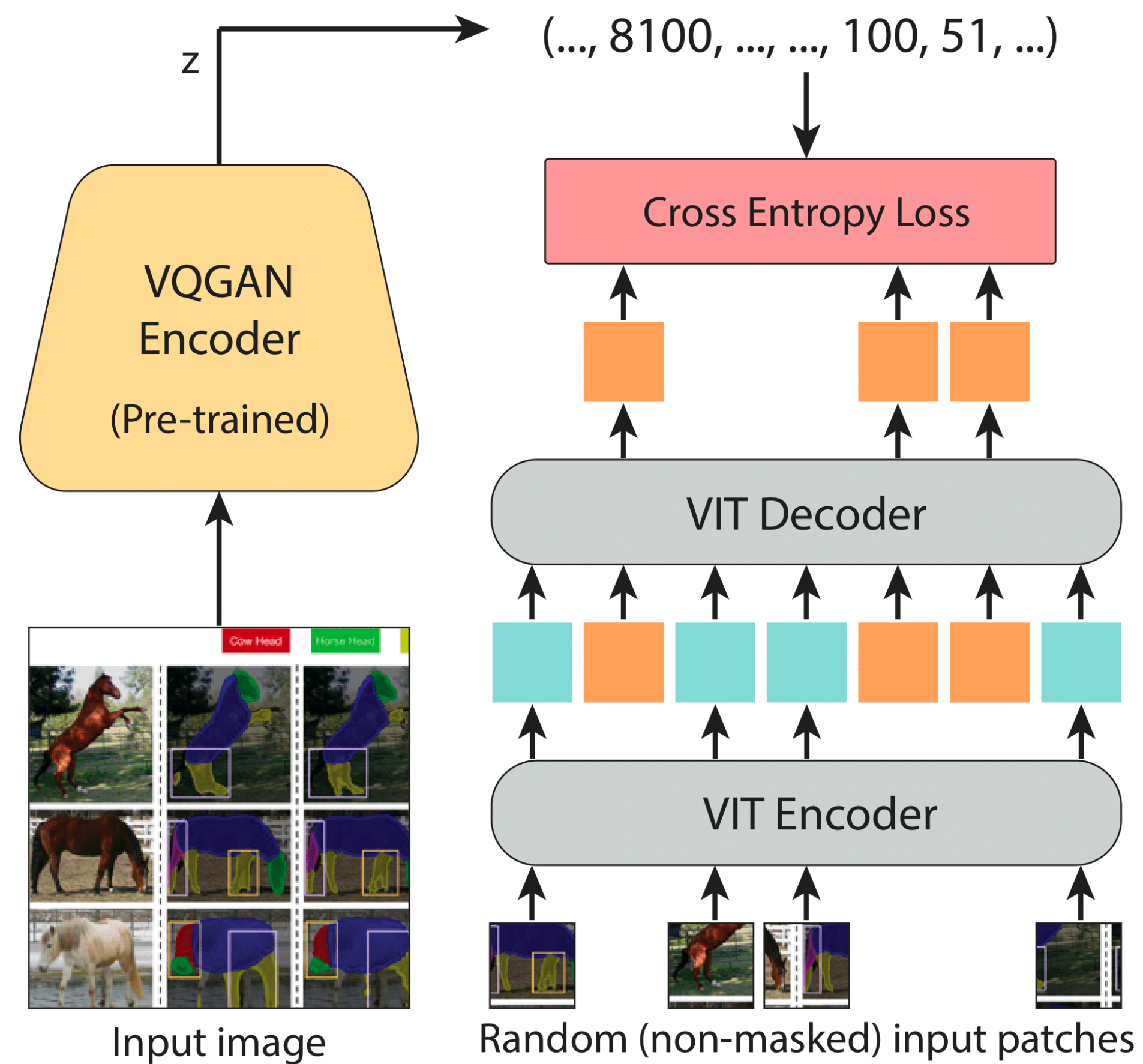
Visual Prompt at Inference



Computer Vision Figures Dataset
: 88k unlabeled figures

Visual Prompting via Image Inpainting

- Inpainting using MAE-VQGAN

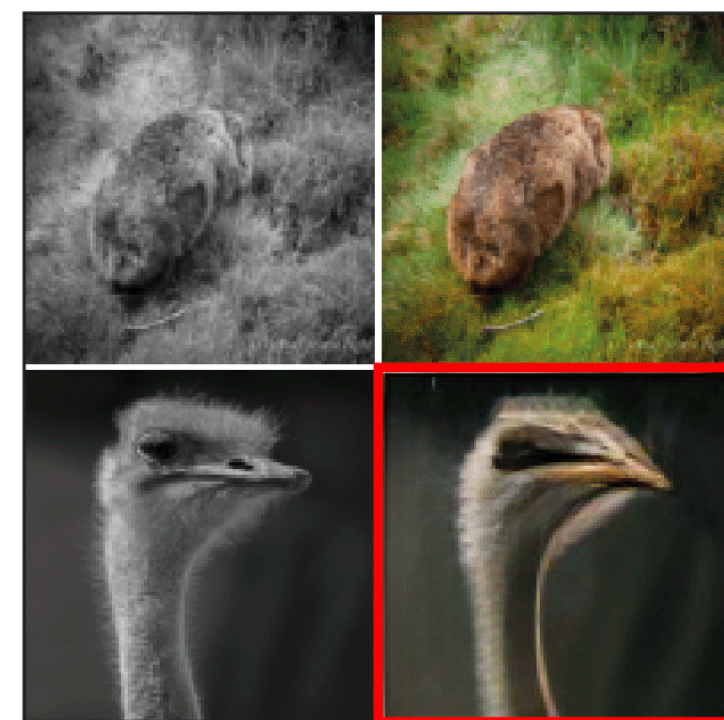
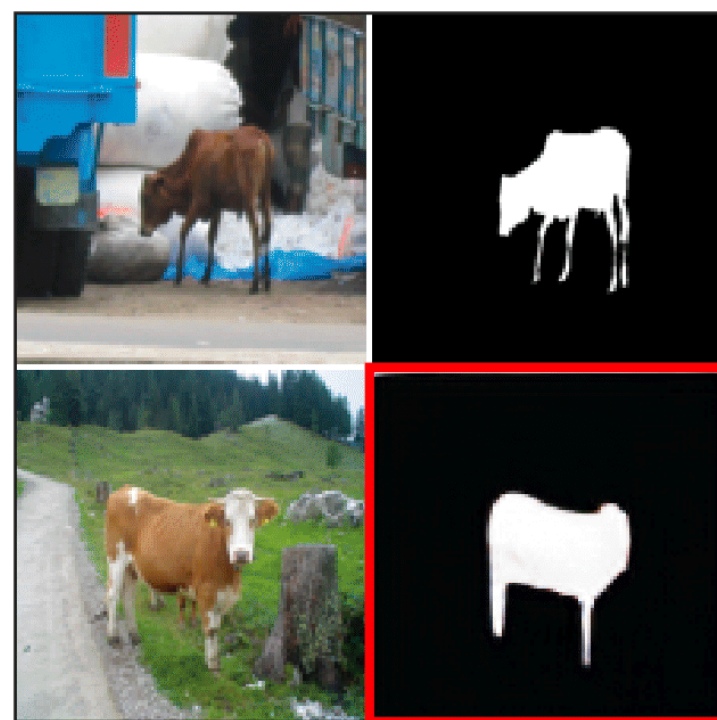


Visual Prompting via Image Inpainting

Pretraining	# Labeled Images	# Shots	Model	Split 0	Split 1	Split 2	Split 3
Unlabeled ImageNet	1	1	Finetune MAE	11.1	13.4	13.0	12.3
	4	4		12.9	15.8	14.3	15.0
	16	16		13.7	16.1	16.8	17.1
Unlabeled Figures	1	1	MAE-VQGAN	32.5	33.8	32.7	27.2
Labeled Pascal 5i (Segmentation masks)	2086 – 5883	1	FWB [36]	51.3	64.5	56.7	52.2
		1	CyCTR [59]	67.2	71.1	57.6	59.0



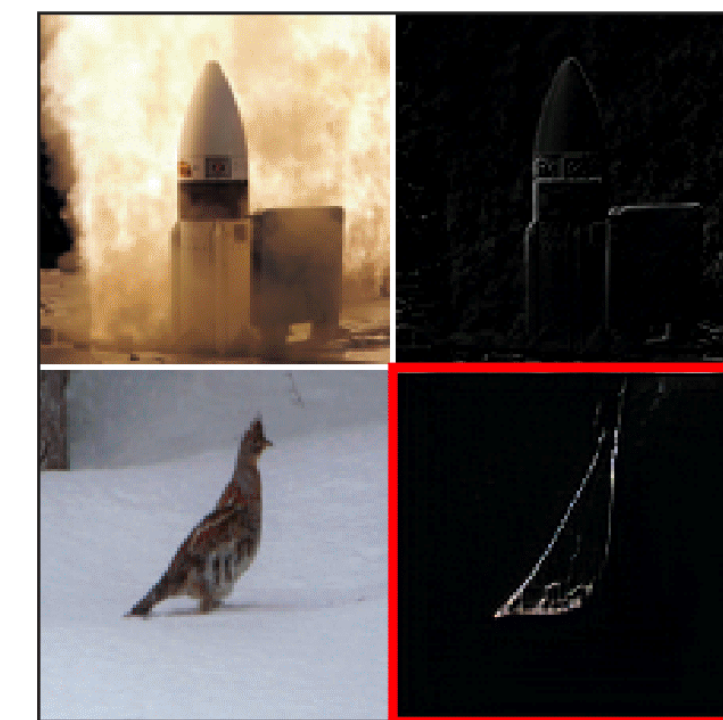
Segmentation



Colorization

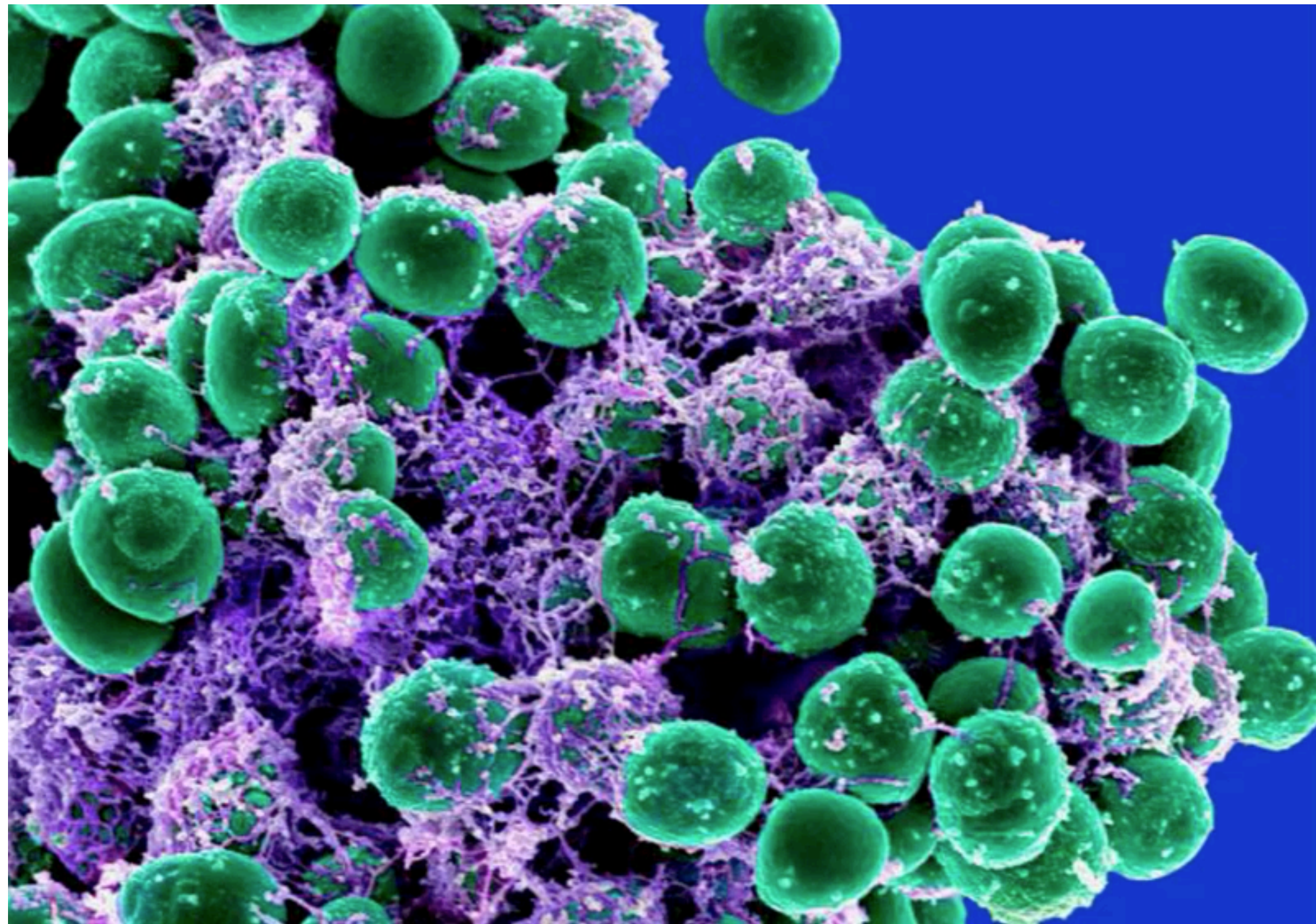


Inpainting



Edge detection

Segment Anything (SAM)

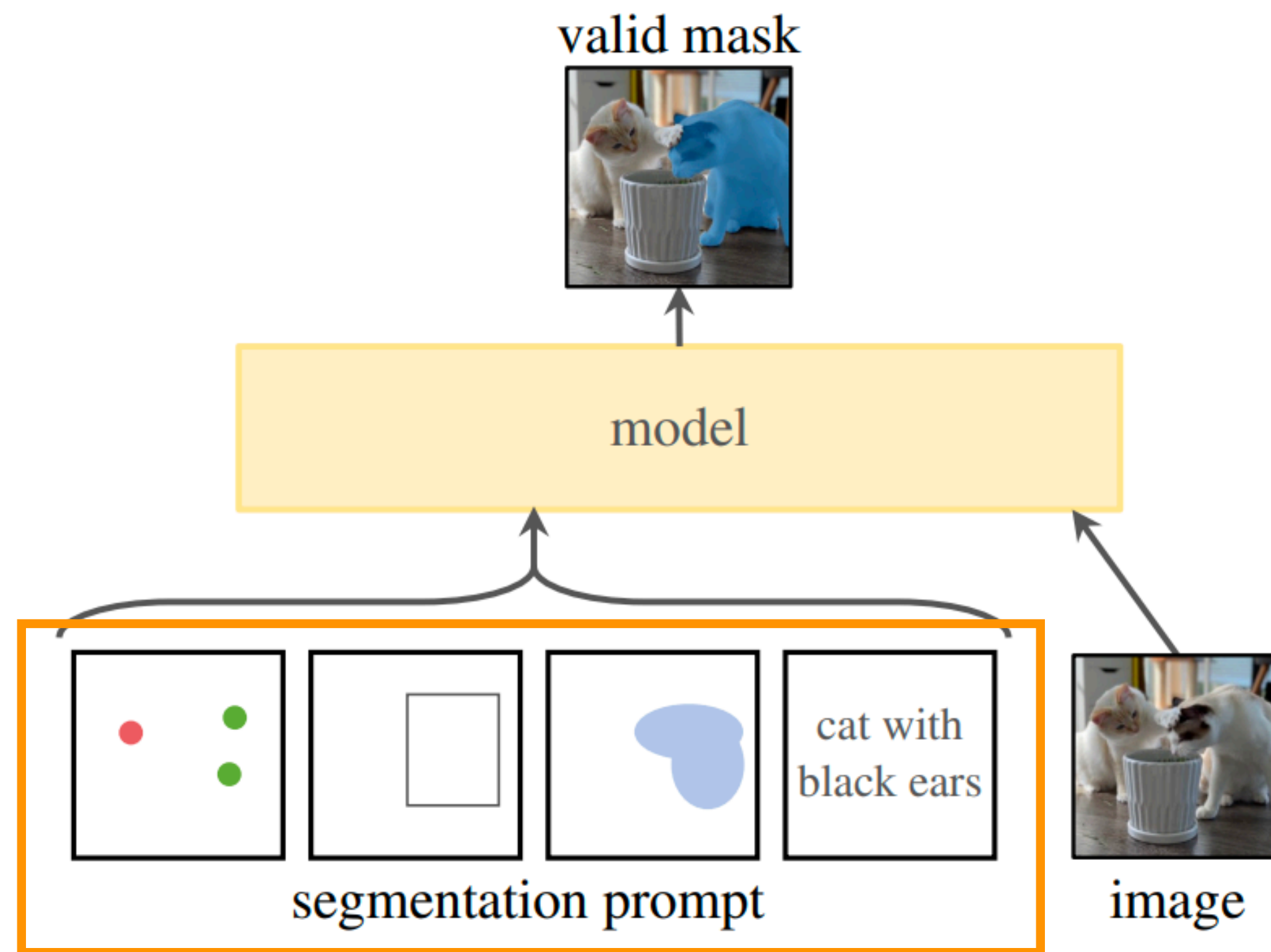


Segment Anything, 2023.

Segment Everything Everywhere All at Once, 2023.

Segment Anything (SAM)

- Goal: build a foundation model for image segmentation



Model is designed and trained to be promptable

It can transfer zero-shot to new image distributions and tasks!

Segment Anything (SAM)

Three components

1. What *task* will enable zero-shot generalization?
2. What is the corresponding *model* architecture?
3. What *data* can power this task and model?

Segment Anything (SAM)

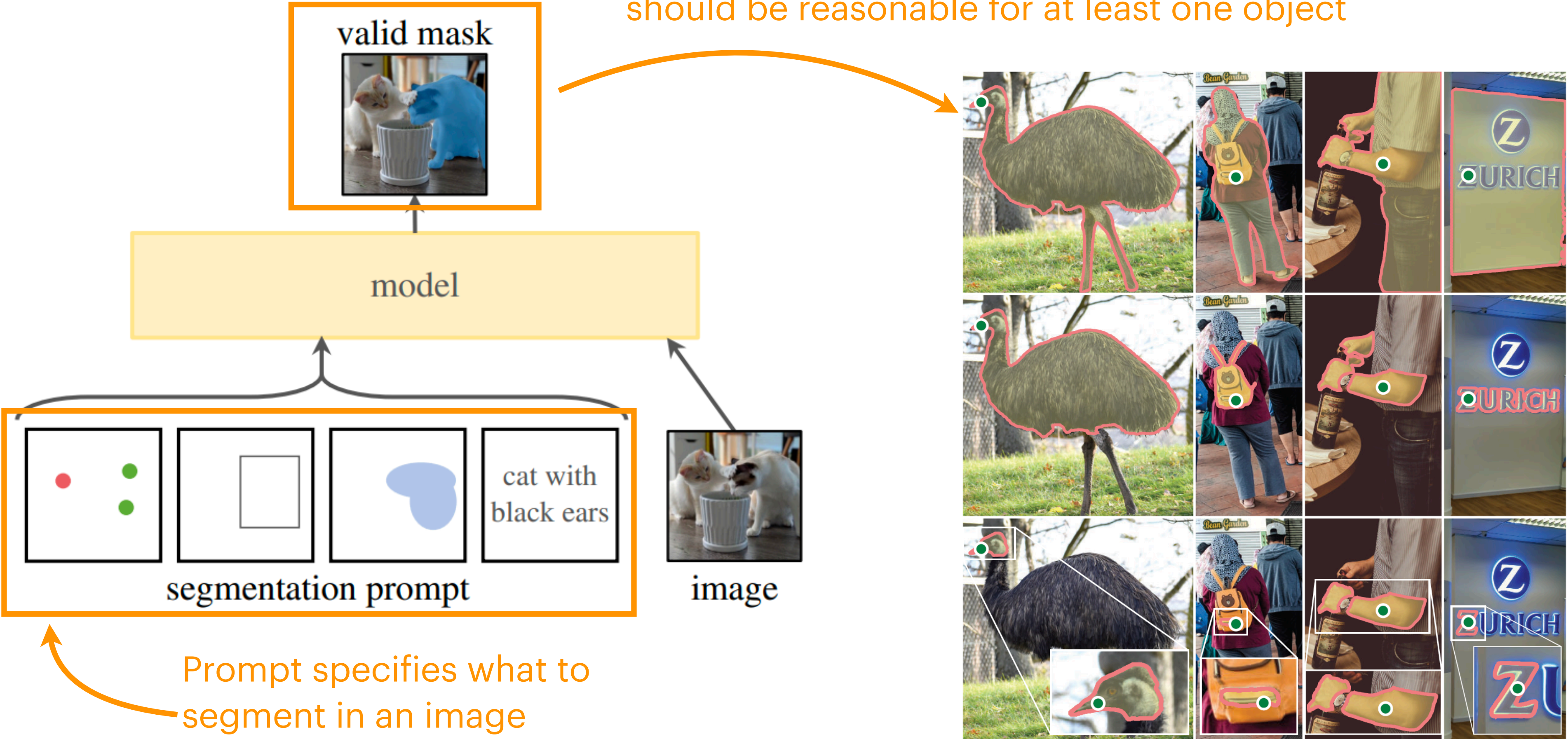
Three components

1. What *task* will enable zero-shot generalization?
—> promptable segmentation task

Segment Anything (SAM)

- Promptable segmentation task: return a *valid* segmentation mask given any segmentation *prompt*

Even when a prompt is *ambiguous*, output should be reasonable for at least one object



Prompt specifies what to segment in an image

Segment Anything (SAM)

Three components

1. What *task* will enable zero-shot generalization?
—> promptable segmentation task
2. What is the corresponding *model* architecture?

Segment Anything (SAM)

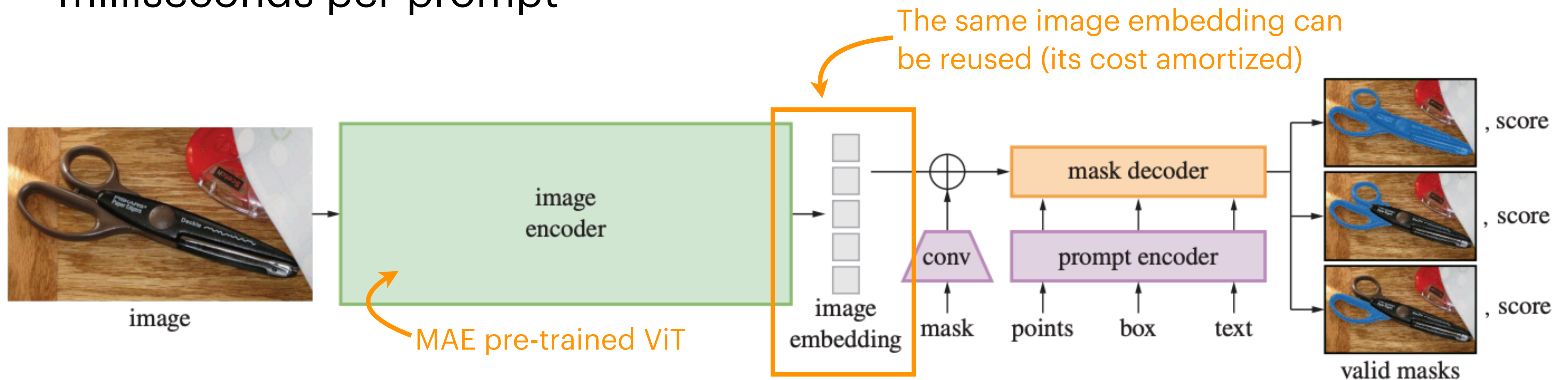
Three components

1. What *task* will enable zero-shot generalization?
—> promptable segmentation task
2. What is the corresponding *model* architecture?
—> support real-time interactive use, flexible prompts, ambiguity-aware

Segment Anything (SAM)

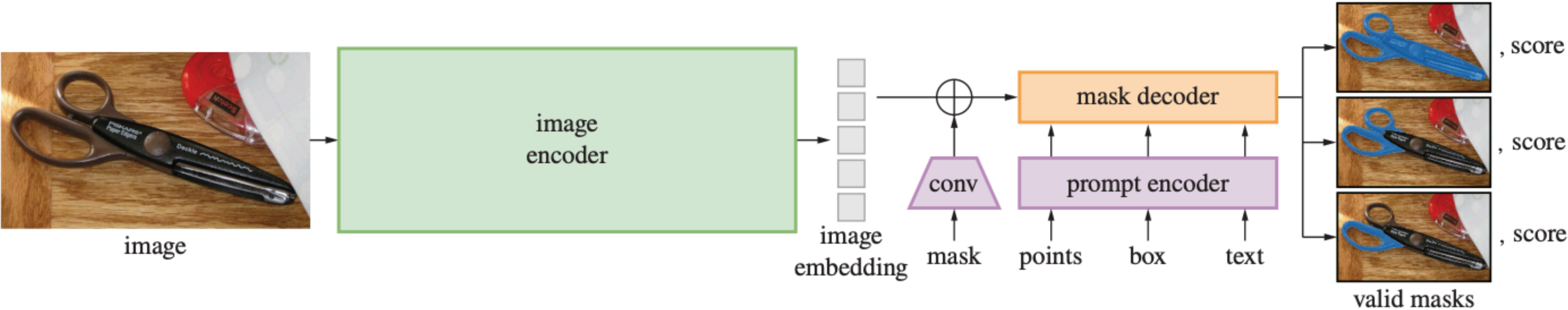
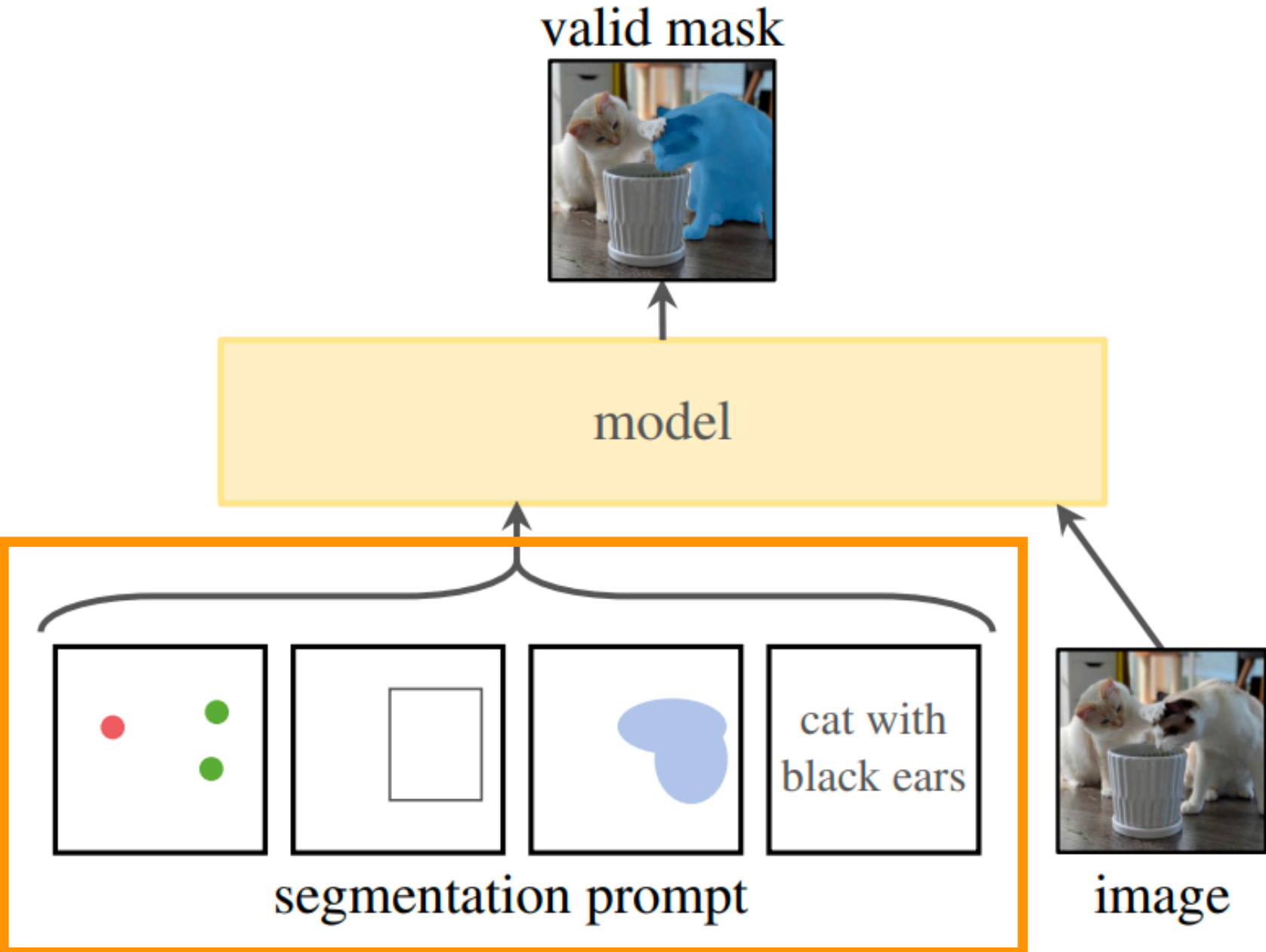
Real-time interactive use: Model is decoupled into

1. One-time heavyweight image encoder
2. Lightweight prompt encoder / mask decoder that can run in a few milliseconds per prompt



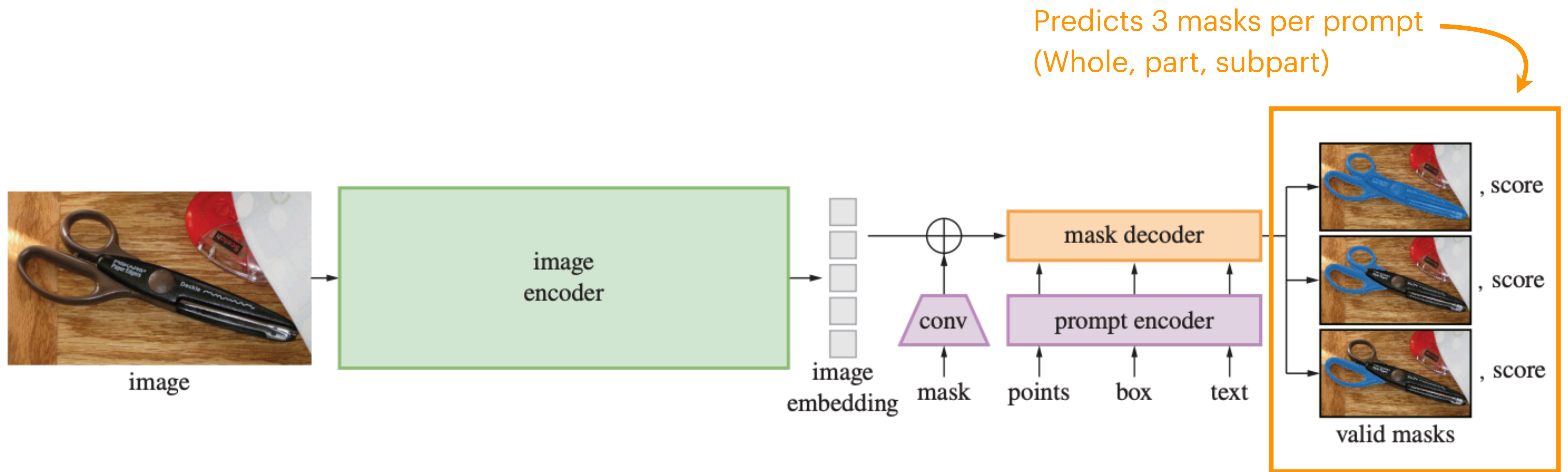
Segment Anything (SAM)

Flexible prompts: points, bounding box, mask, text (not released)



Segment Anything (SAM)

Ambiguity-aware: designed to predict multiple output masks for a single prompt



Segment Anything (SAM)

Three components

1. What *task* will enable zero-shot generalization?
—> promptable segmentation task
2. What is the corresponding *model* architecture?
—> support real-time interactive use, flexible prompts, ambiguity-aware
3. What *data* can power this task and model?

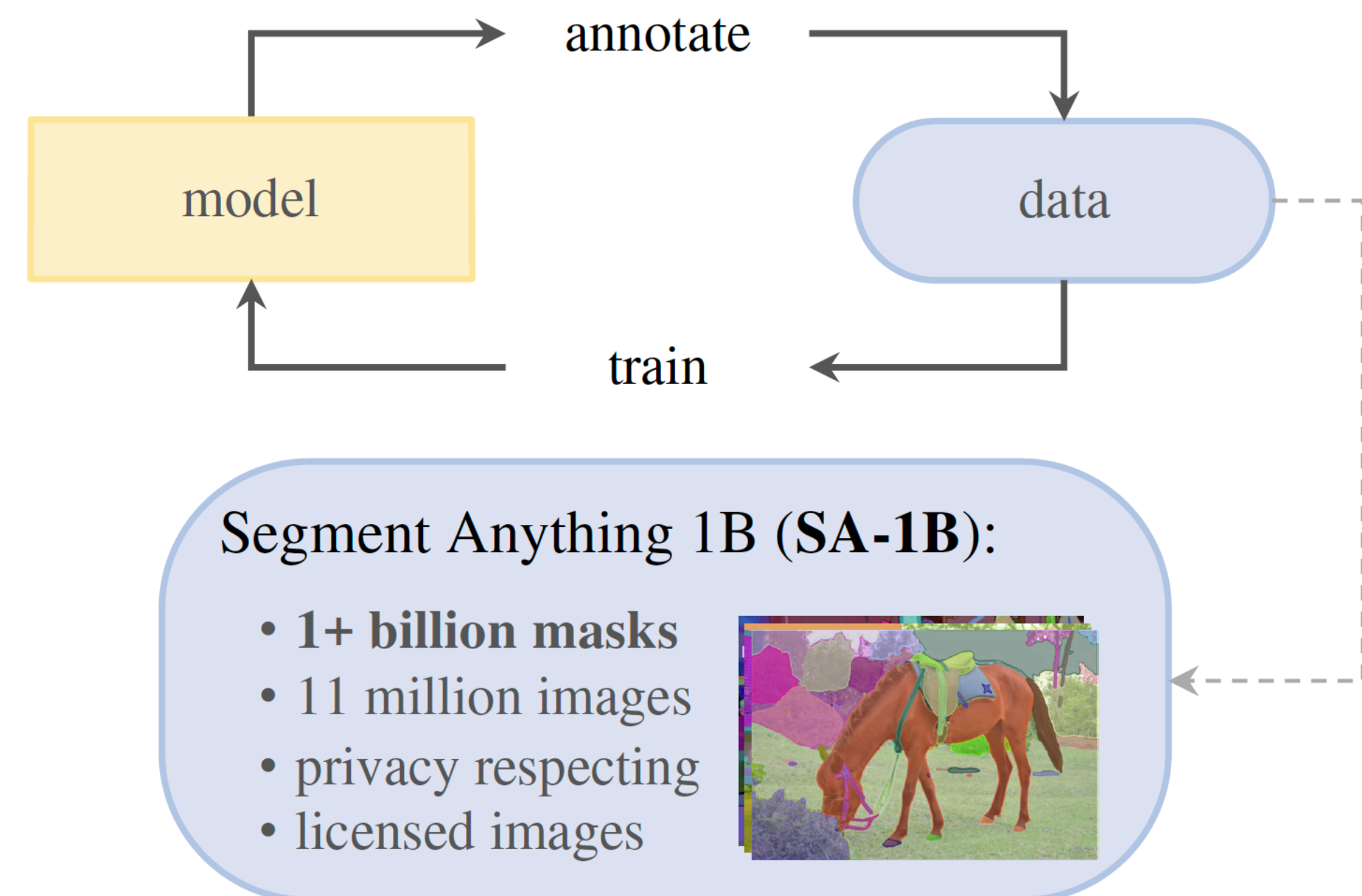
Segment Anything (SAM)

Three components

1. What *task* will enable zero-shot generalization?
—> promptable segmentation task
2. What is the corresponding *model* architecture?
—> support real-time interactive use, flexible prompts, ambiguity-aware
3. What *data* can power this task and model?
—> 11M images, 1.1B masks

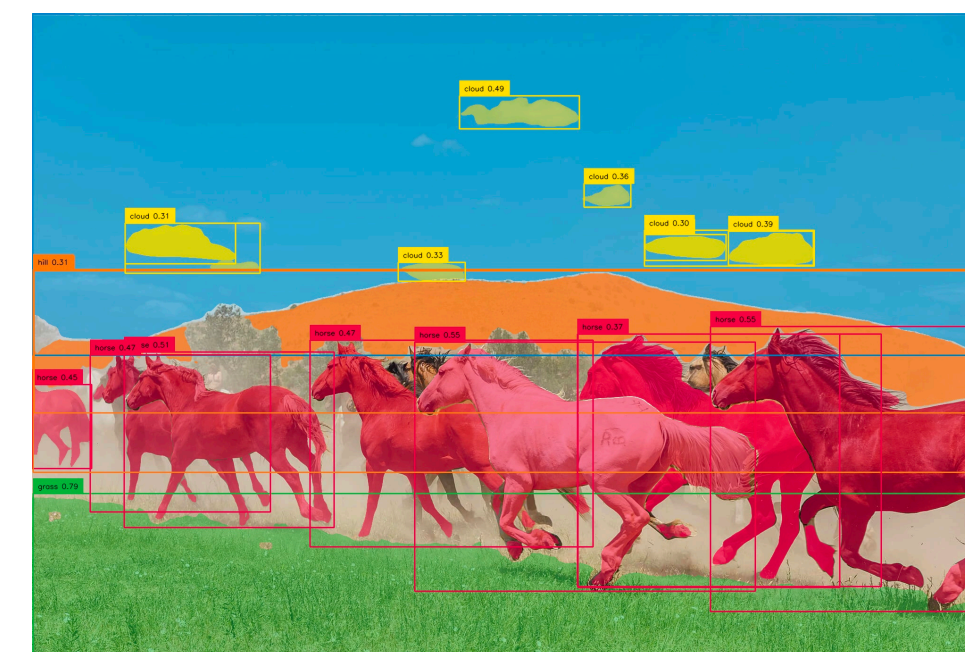
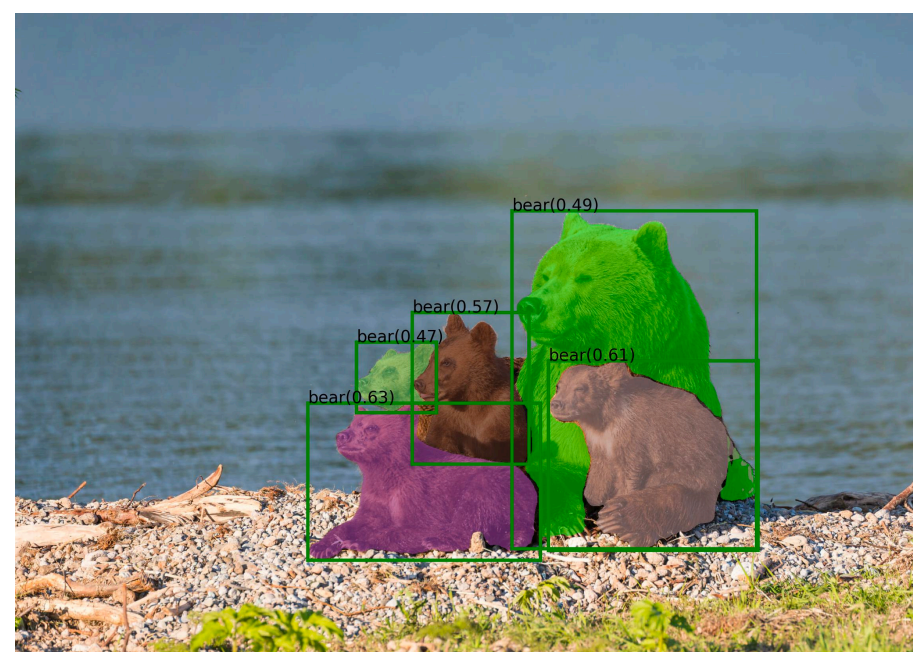
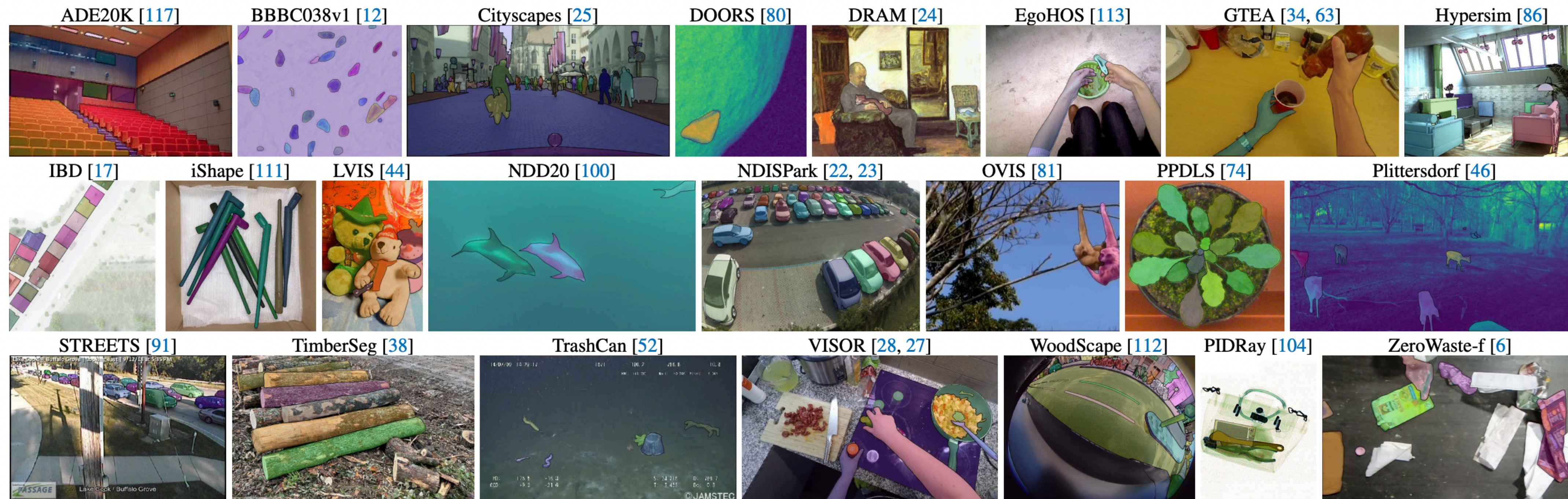
Segment Anything (SAM)

- SA-1B Dataset: 11M images, 1.1B masks
- Three stages
 - (1) model-assisted manual annotation stage
 - (2) semi-automatic stage: mix of predated masks and model-assisted annotation
 - (3) fully automatic stage



Segment Anything (SAM)

Zero-shot transfer to novel image distributions and tasks



Segment Anything (SAM)

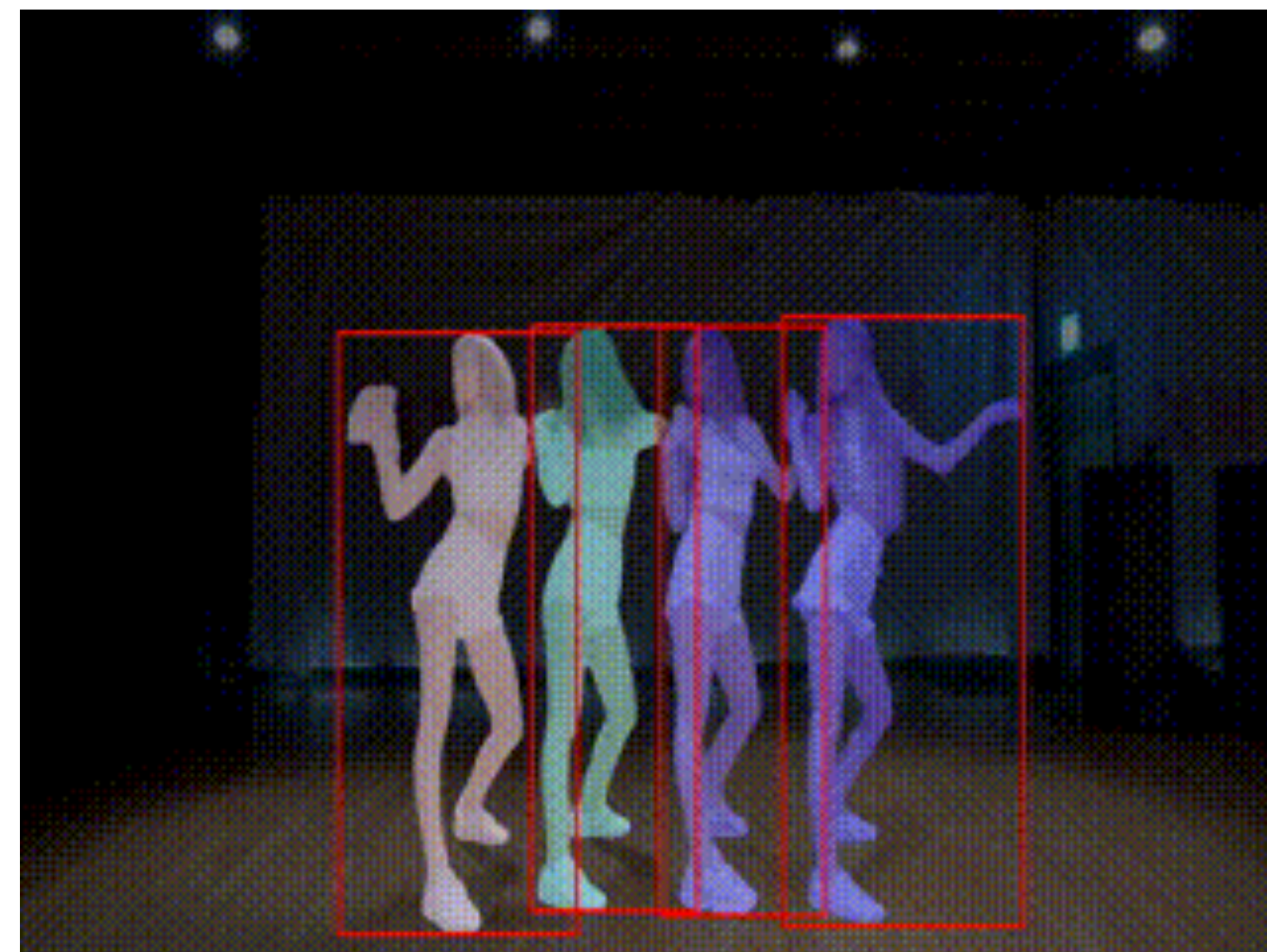
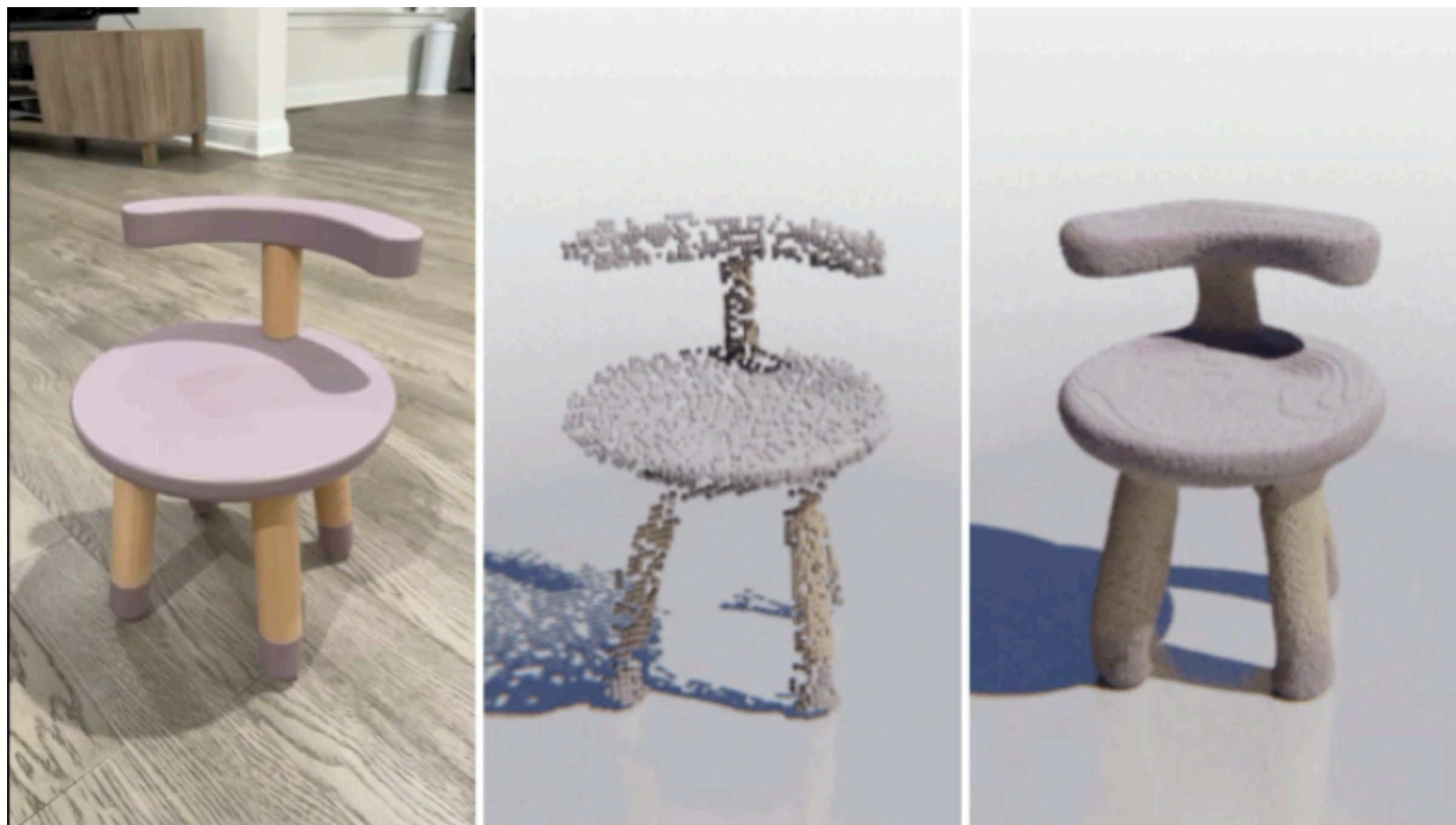
- Flexible integration!



Segment Anything (SAM)



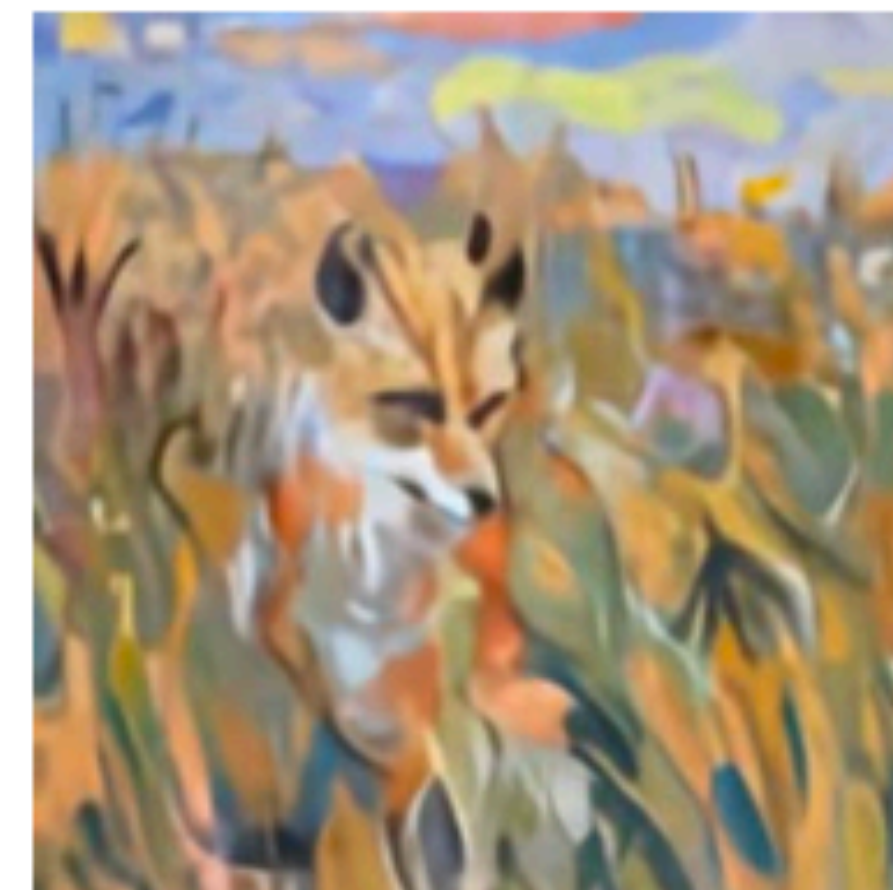
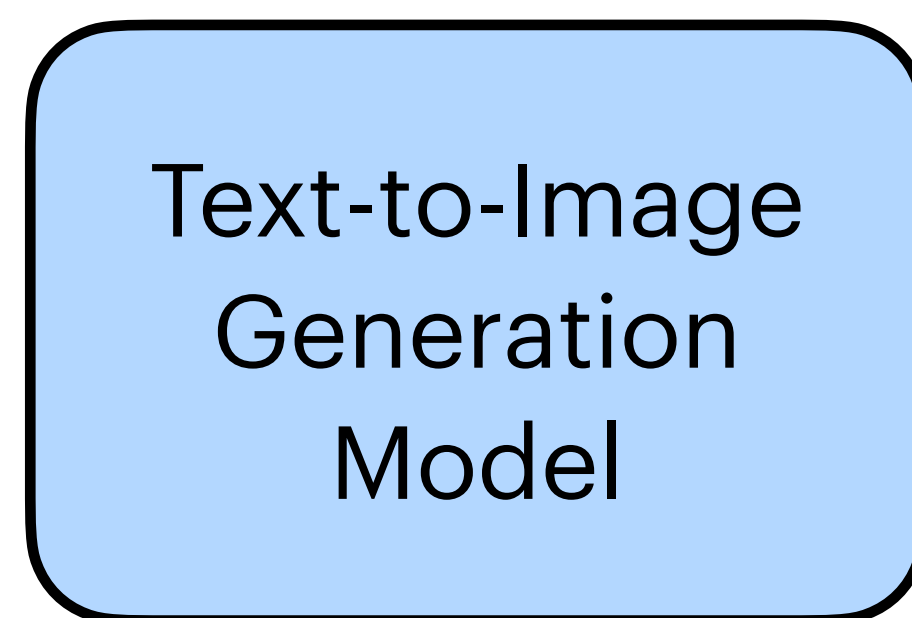
Segment Anything (SAM)



GLIGEN

- *Promptable* image generation

Text Prompt:
“A painting of a fox sitting
in a field at sunrise in the
style of Cluade Monet”



e.g. Stable Diffusion

GLIGEN

- *Promptable* image generation

Text Prompt:
"A painting of a fox sitting
in a field at sunrise in the
style of Cluade Monet"



Text-to-Image
Generation
Model

e.g. Stable Diffusion



Increase its controllability!

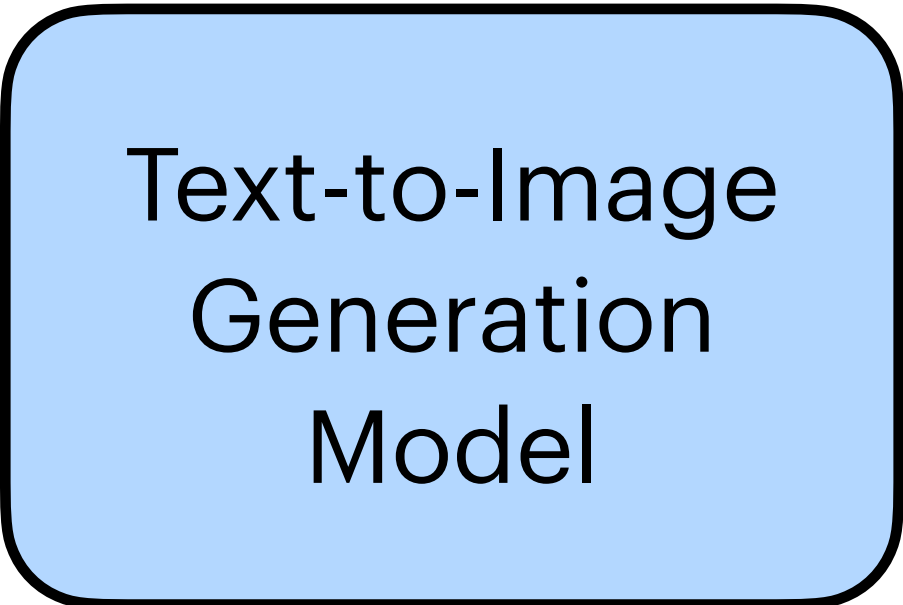
GLIGEN

- *Promptable* image generation

Text Prompt:
“A painting of a fox sitting
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style of Cluade Monet”



Increase its controllability!



e.g. Stable Diffusion



GLIGEN

- Goal: enable new conditional input modalities to existing pre-trained diffusion models



(c) Caption: "Elon Musk and Emma Watson on a movie poster"
Grounded text: **Elon Musk**, **Emma Watson**; Grounded style image: **blue inset**



(d) Caption: "a baby girl / monkey / Horner Simpson / is scratching her/its head"
Grounded keypoints: **plotted dots on the left image**



(e) Caption: "A vibrant colorful bird sitting on tree branch"
Grounded depth map: **the left image**



(f) Caption: "A young boy with white powder on his face looks away"
Grounded HED map: **the left image**



(g) Caption: "Cars park on the snowy street"
Grounded normal map: **the left image**



(h) Caption: "A living room filled with lots of furniture and plants"
Grounded semantic map: **the left image**

GLIGEN

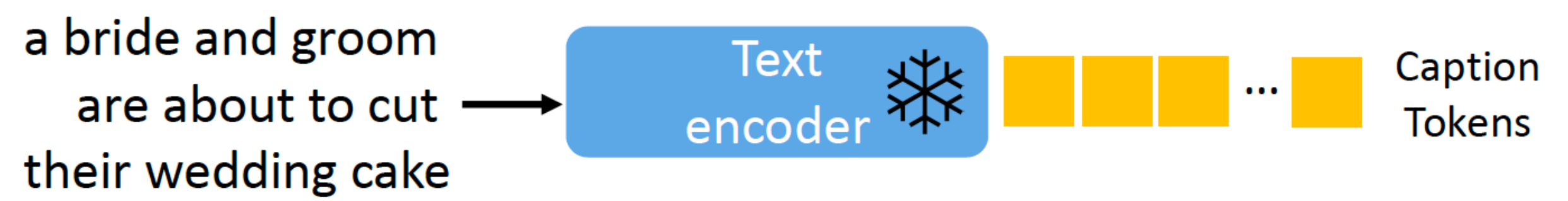


Instruction: $\mathbf{y} = (\mathbf{c}, \mathbf{e})$, with

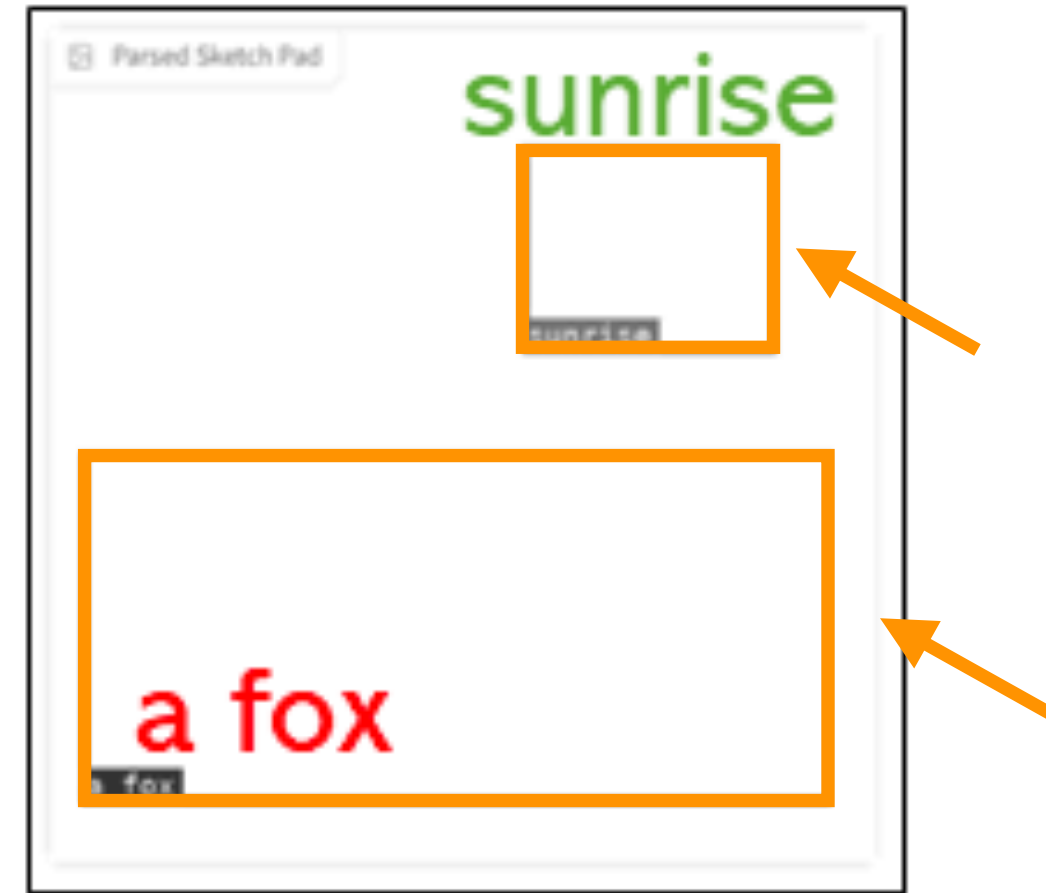
Caption: $\mathbf{c} = [c_1, \dots, c_L]$

Grounding: $\mathbf{e} = [(e_1, \mathbf{l}_1), \dots, (e_N, \mathbf{l}_N)]$

Semantic Information
(e.g. text, example image)



GLIGEN



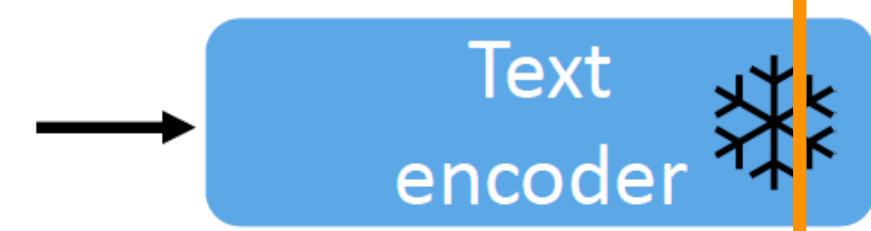
Instruction: $\mathbf{y} = (\mathbf{c}, \mathbf{e})$, with

Caption: $\mathbf{c} = [c_1, \dots, c_L]$

Grounding: $\mathbf{e} = [(e_1, \mathbf{l}_1), \dots, (e_N, \mathbf{l}_N)]$

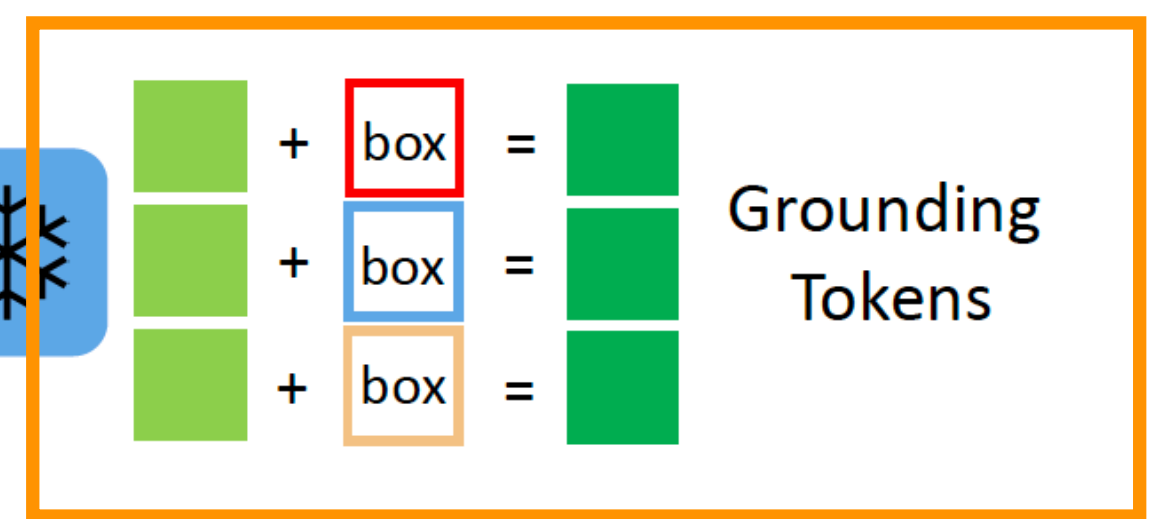
Grounding spatial configuration
(e.g. bounding box, keypoints)

Semantic Information
(e.g. text, example image)

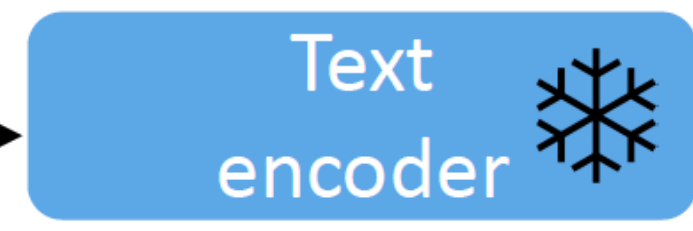


$$h^e = \text{MLP}(f_{\text{text}}(e), \text{Fourier}(\mathbf{l}))$$

Text feature + bounding box

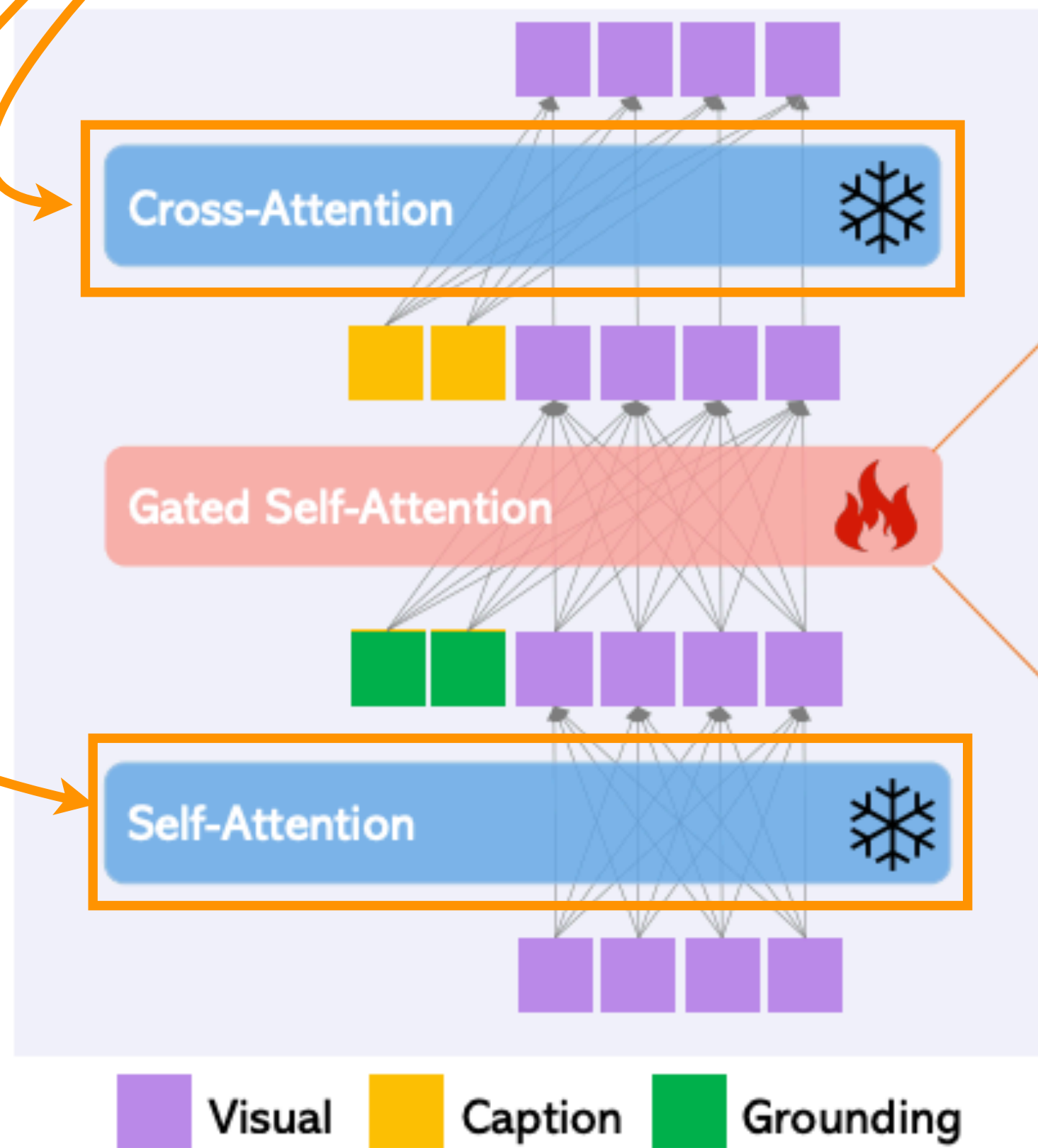


a bride and groom
are about to cut
their wedding cake

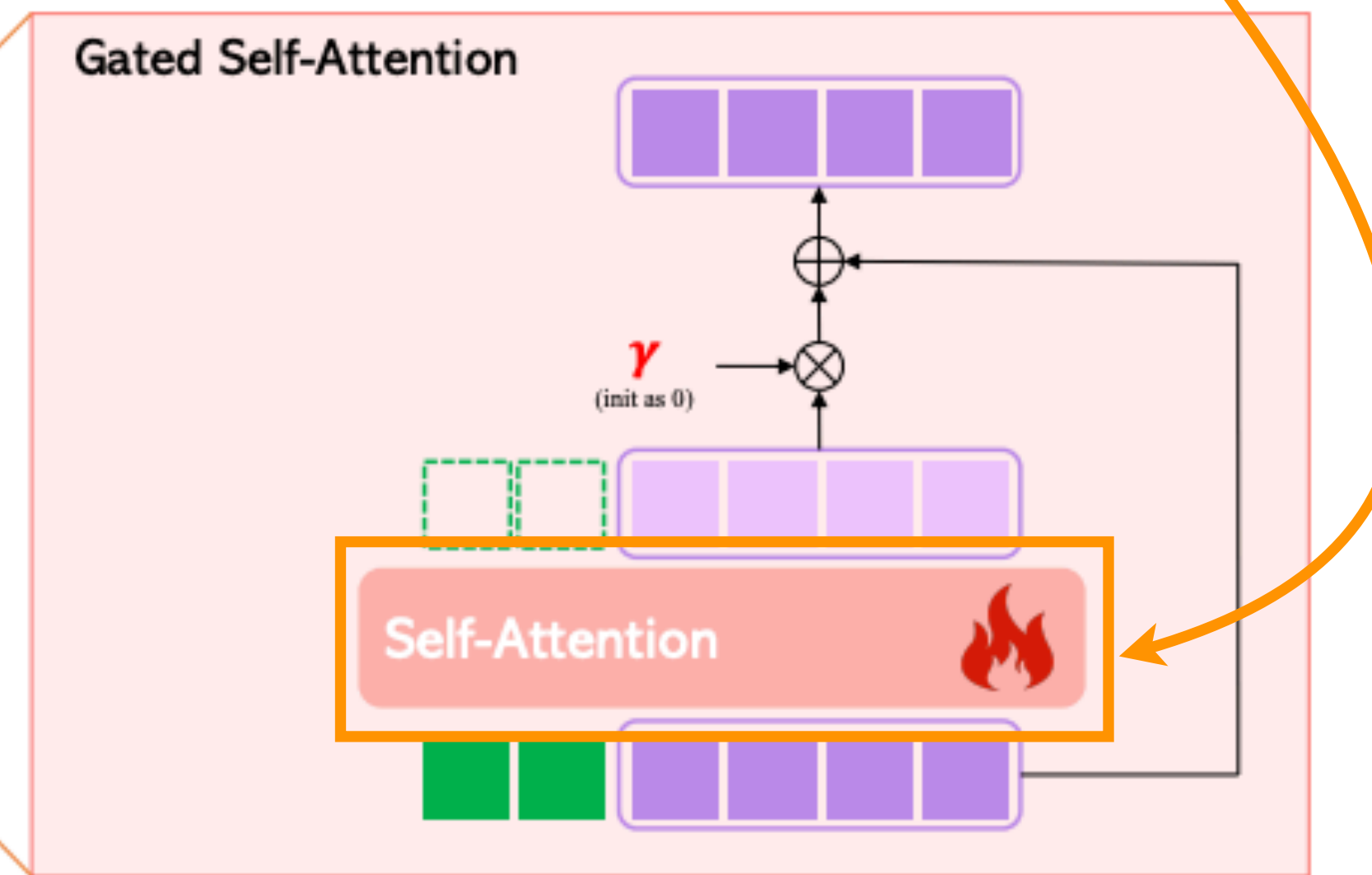


GLIGEN

Original attention layers remain frozen



Add a new gated self-attention layer to take in the *new conditional information*



$$v = v + \beta \cdot \tanh(\gamma) \cdot \text{TS}(\text{SelfAttn}([v, h^e]))$$

GLIGEN

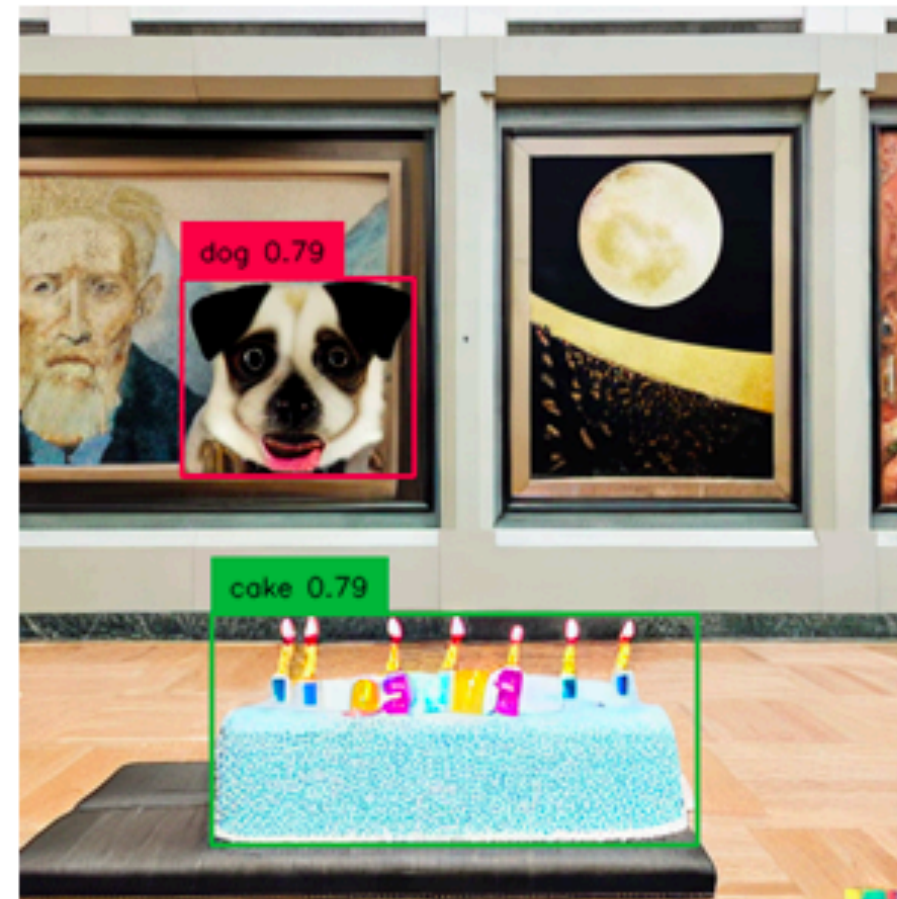
Training Data

- Bounding box: Flickr, VG, SBU, O365, CC3M
- Keypoints: COCO2017
- HED edge map: CC3M + pytorch-hed
- Canny edge map: CC3M + cv.Canny()
- Semantic map: ade20k + BLIP
- Depth map: CC3M + MiDas
- Normal map: DIODE + BLIP

GLIGEN with other systems



Grounding
DINO



Detect: dog, cake

GLIGEN with other systems



Grounding
DINO



Detect: dog, cake

GLIGEN



Generation:

Box1: cat

Box2: rose

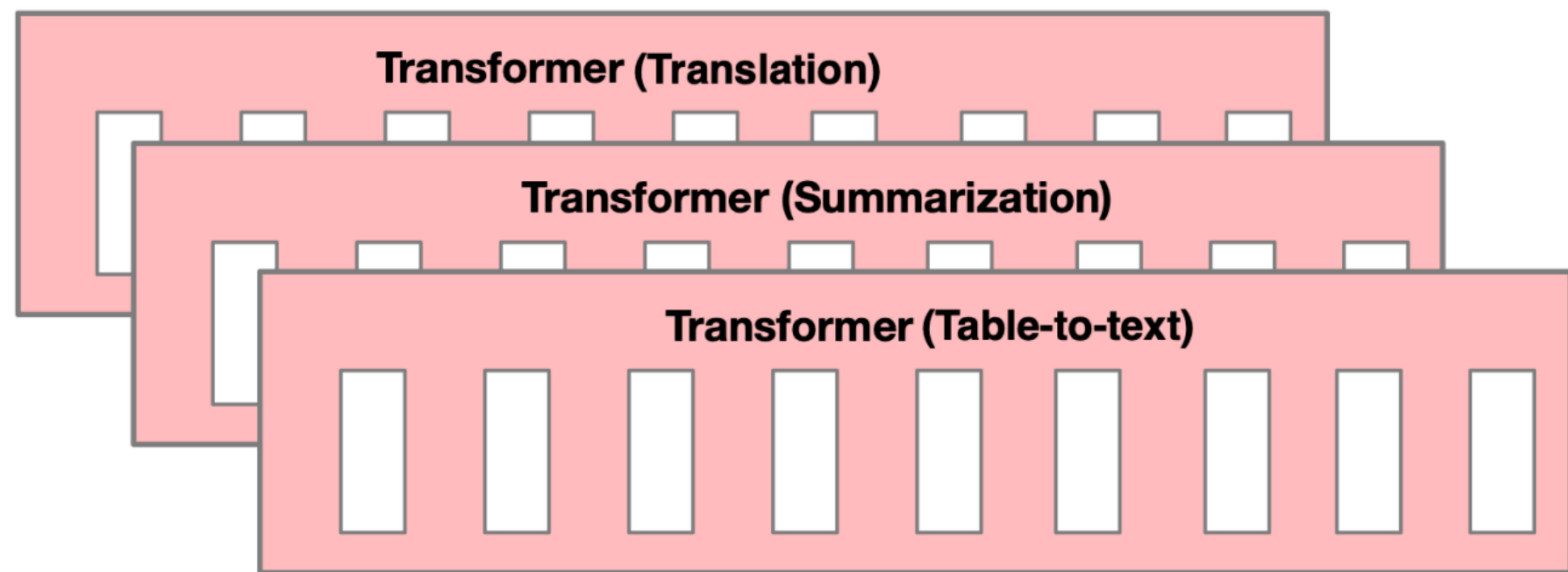
Parameter-efficient fine-tuning (PEFT)

Visual Prompt Learning

Prefix / Prompt Tuning

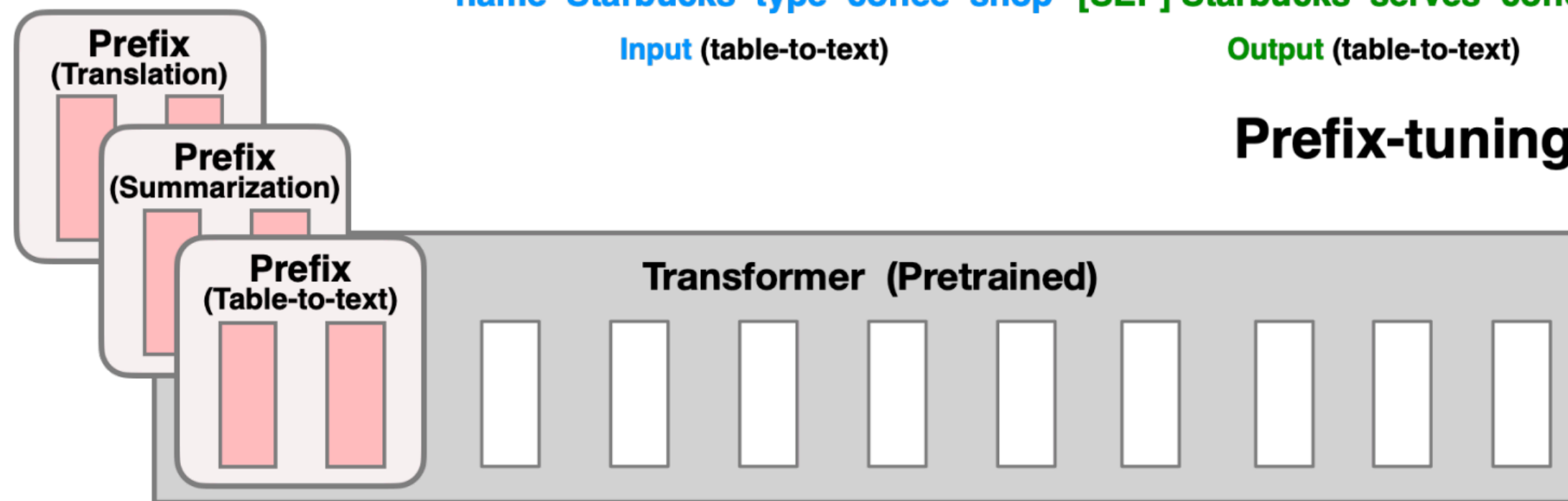
Language

Fine-tuning



name Starbucks type coffee shop [SEP] Starbucks serves coffee
Input (table-to-text) Output (table-to-text)

Prefix-tuning



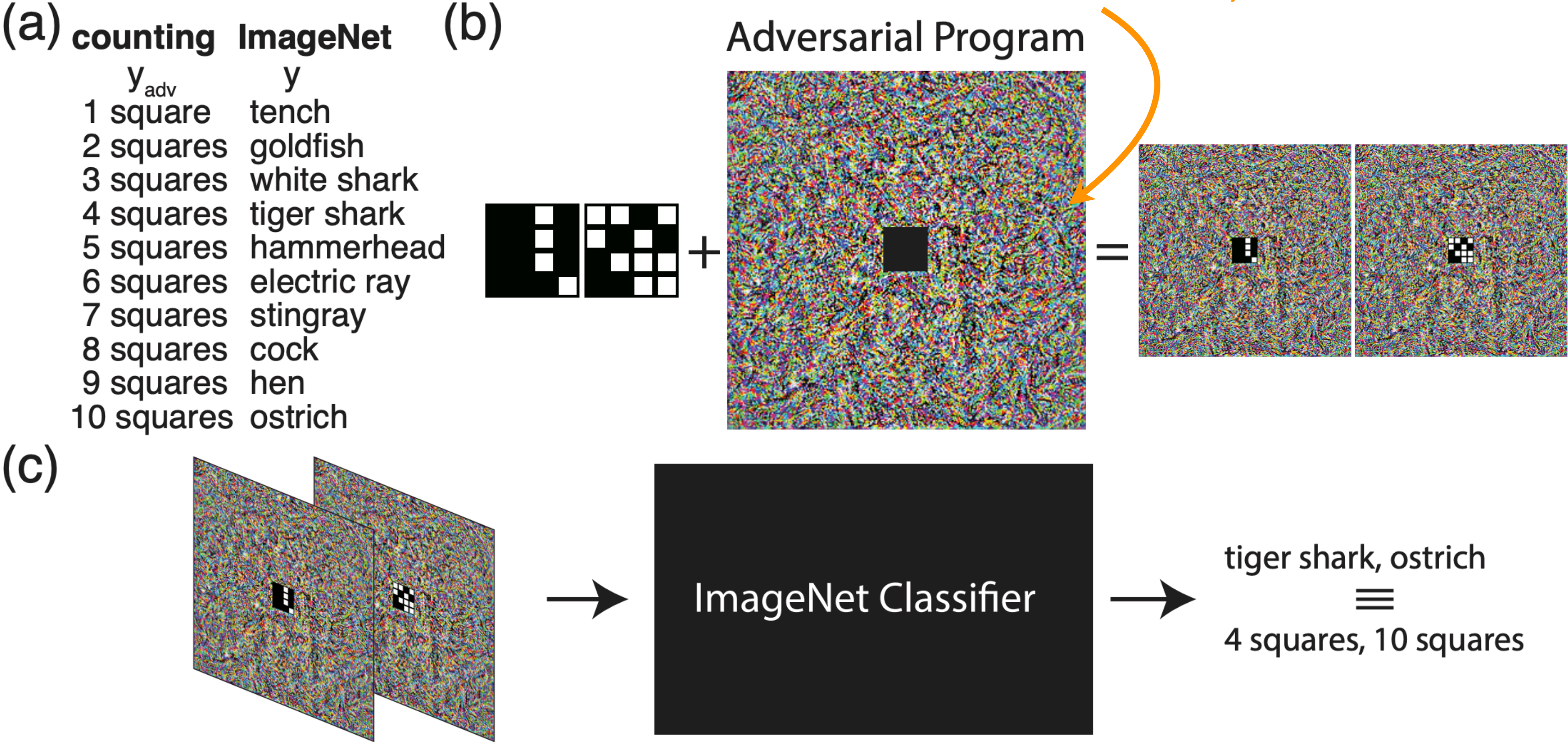
name Starbucks type coffee shop [SEP] Starbucks serves coffee
Input (table-to-text) Output (table-to-text)

Vision

- Pixel prompts
- Embedding prompts

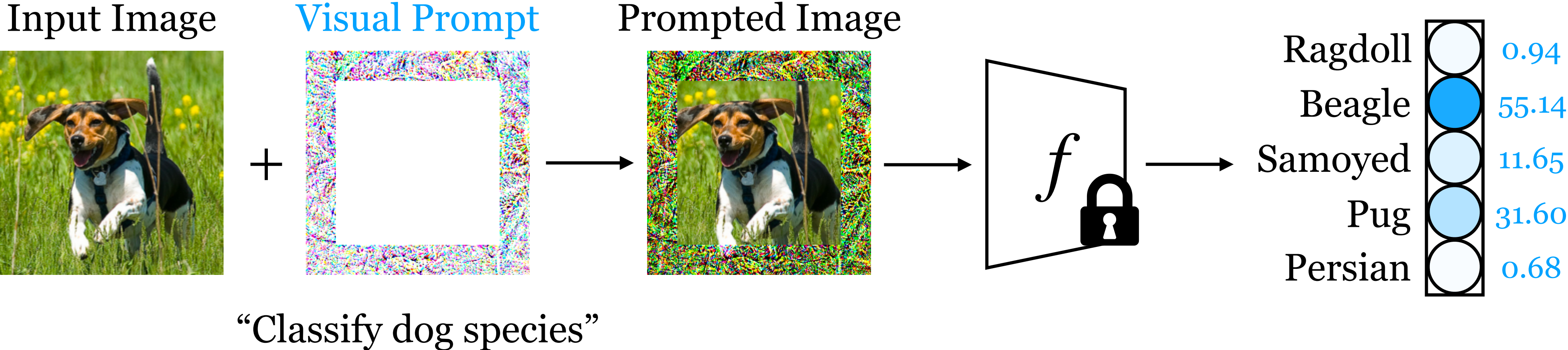
Adversarial Reprogramming

Reprograms the target model to perform a task chosen by the attacker



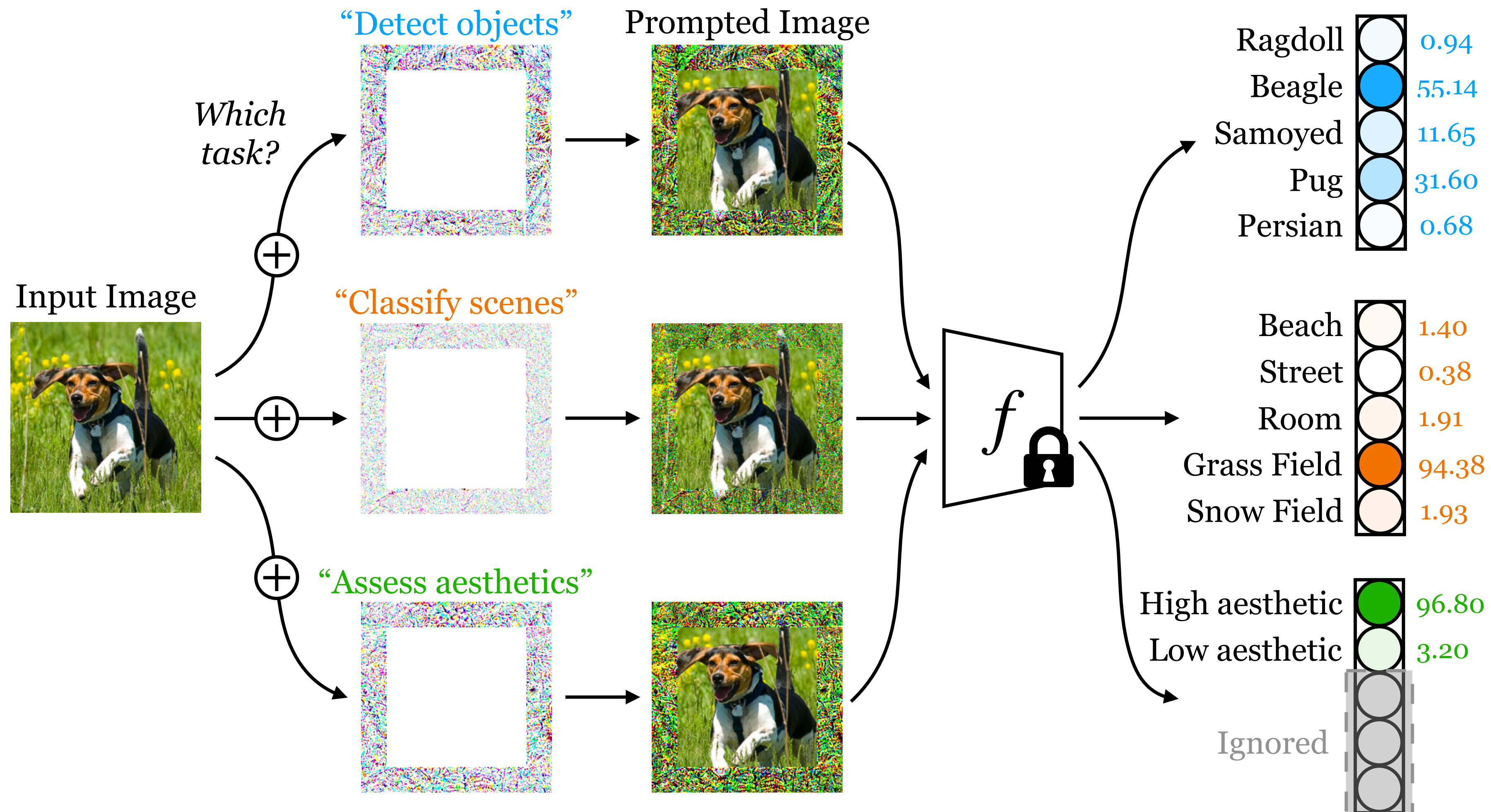
Prompt Learning in Pixel Space

- A visual prompt can be *learned in pixel space*



Prompt Learning in Pixel Space

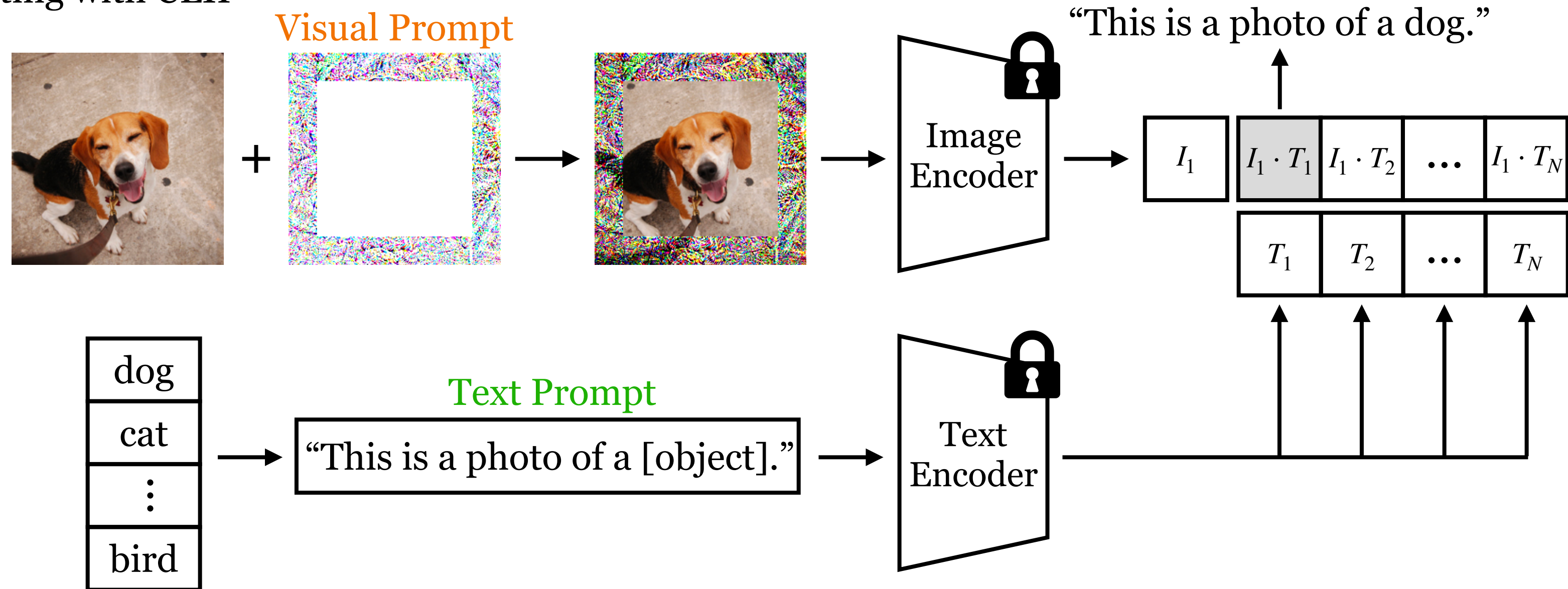
- Prompt = a continuous task-specific vector



Prompt Learning in Pixel Space

- Learn a single image perturbation (“soft prompt”) via backpropagation while having the model weights frozen

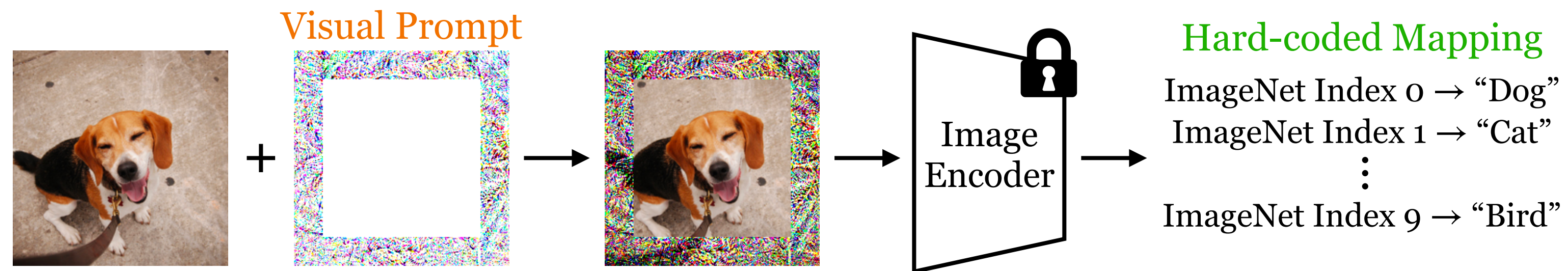
(a) Prompting with CLIP



Prompt Learning in Pixel Space

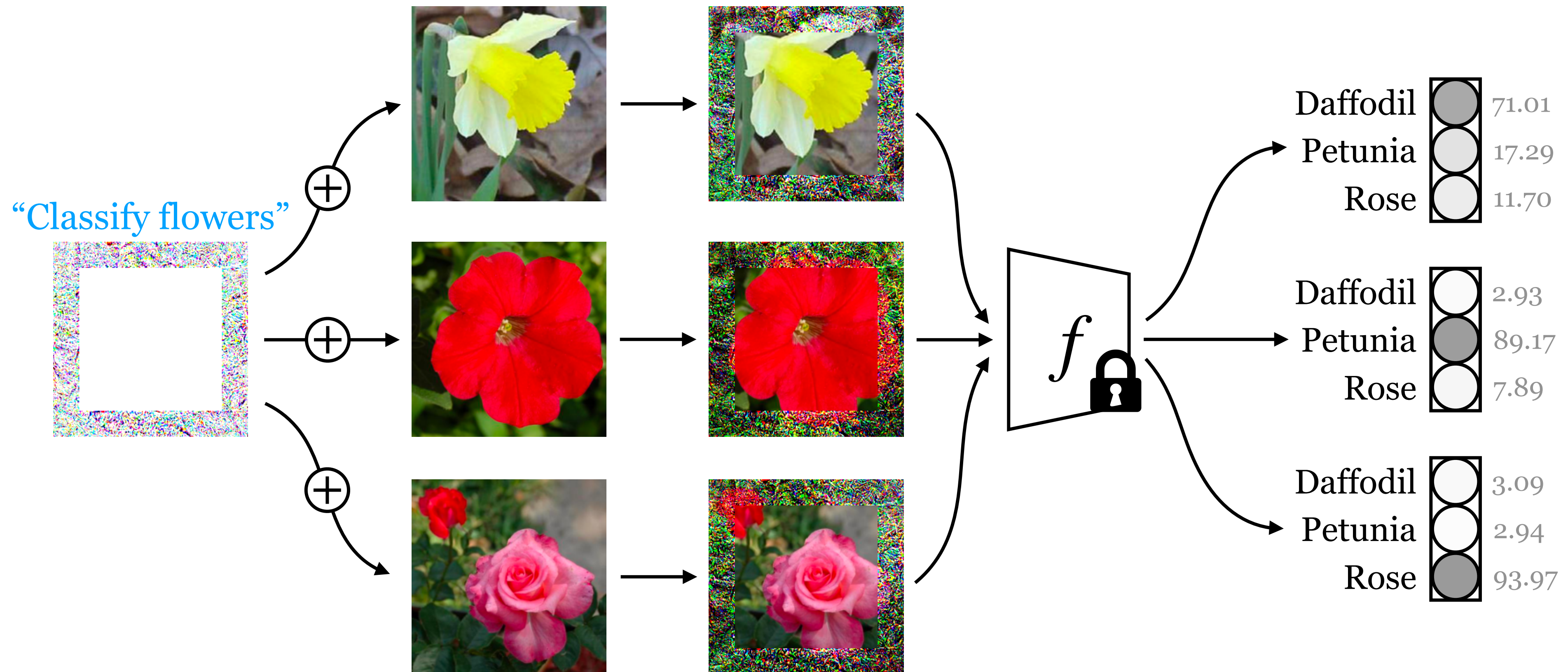
- Learn a single image perturbation (“soft prompt”) via backpropagation while having the model weights frozen

(b) Prompting (adversarial reprogramming) with vision models



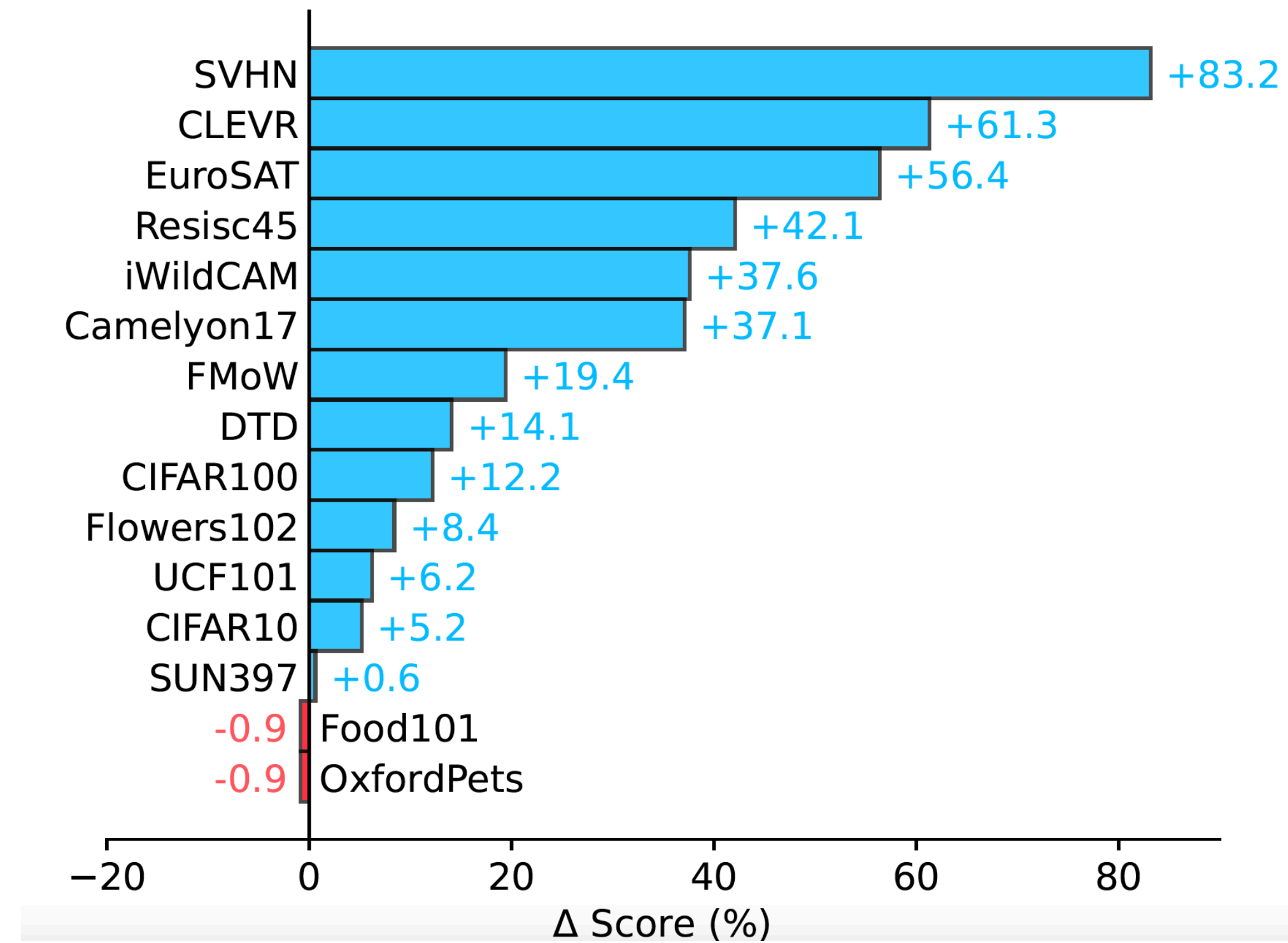
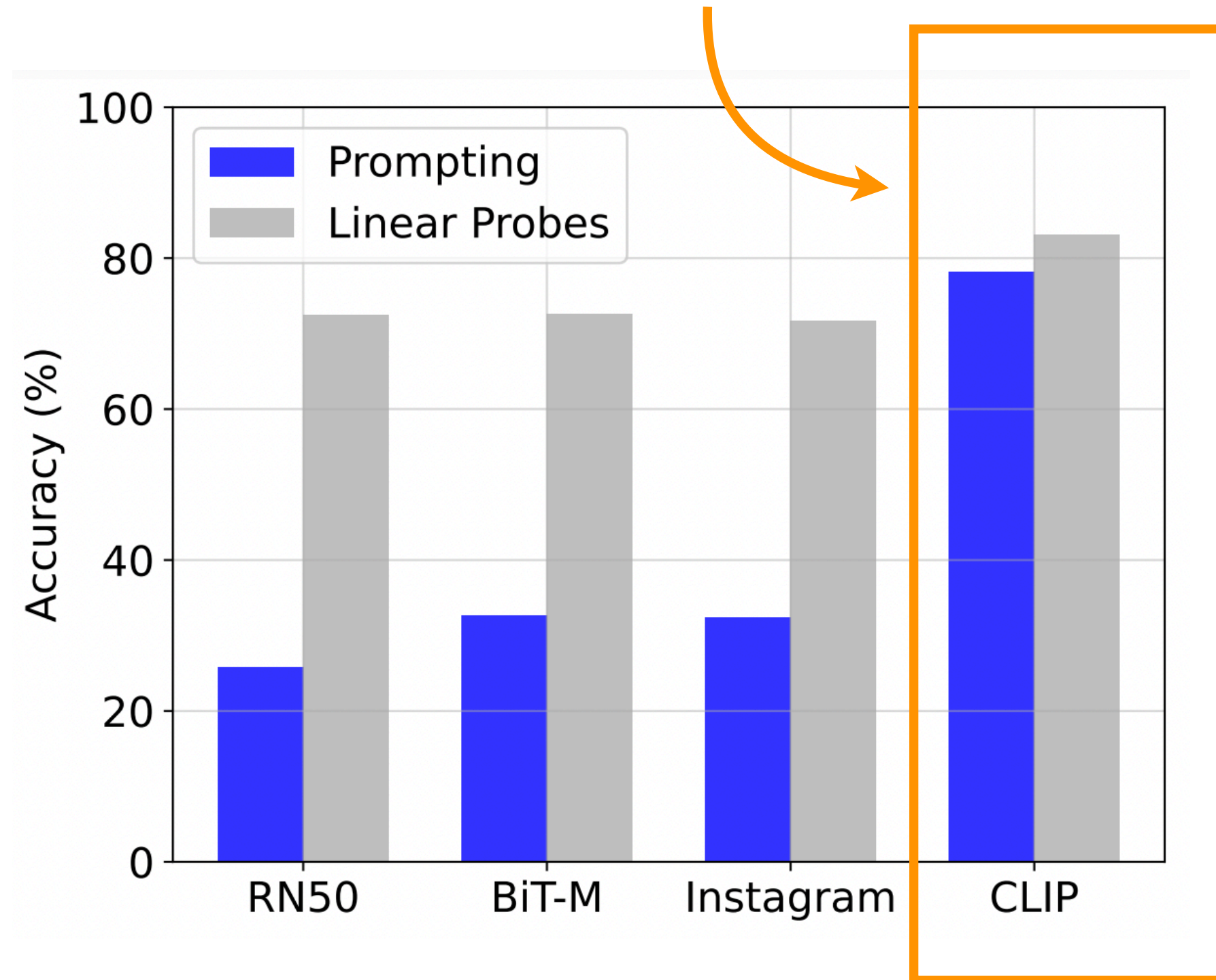
Prompt Learning in Pixel Space

- During inference, the optimized prompt is added to all test-time images



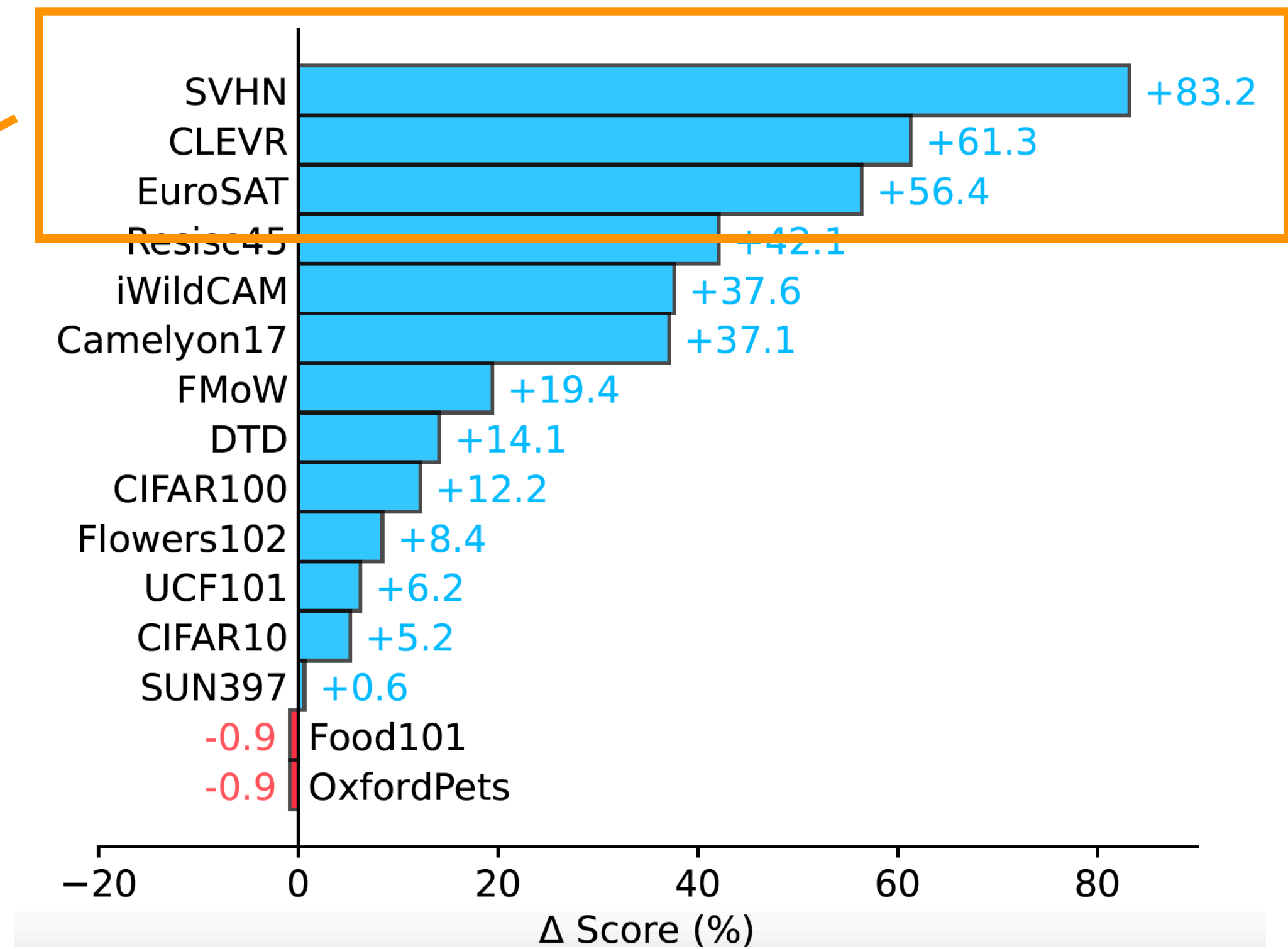
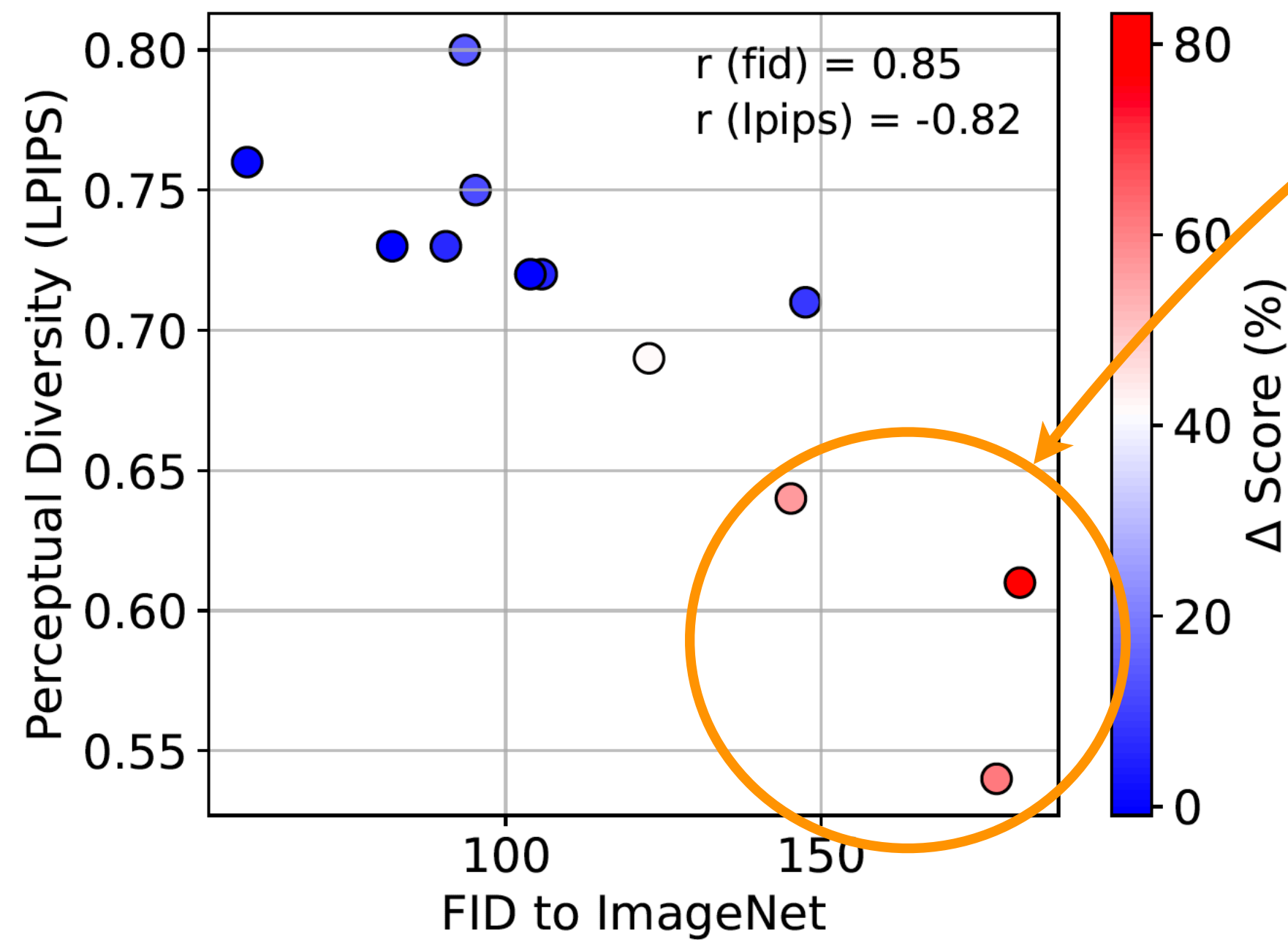
Prompt Learning in Pixel Space

CLIP (vision-language model) is particularly effective compared to vision models

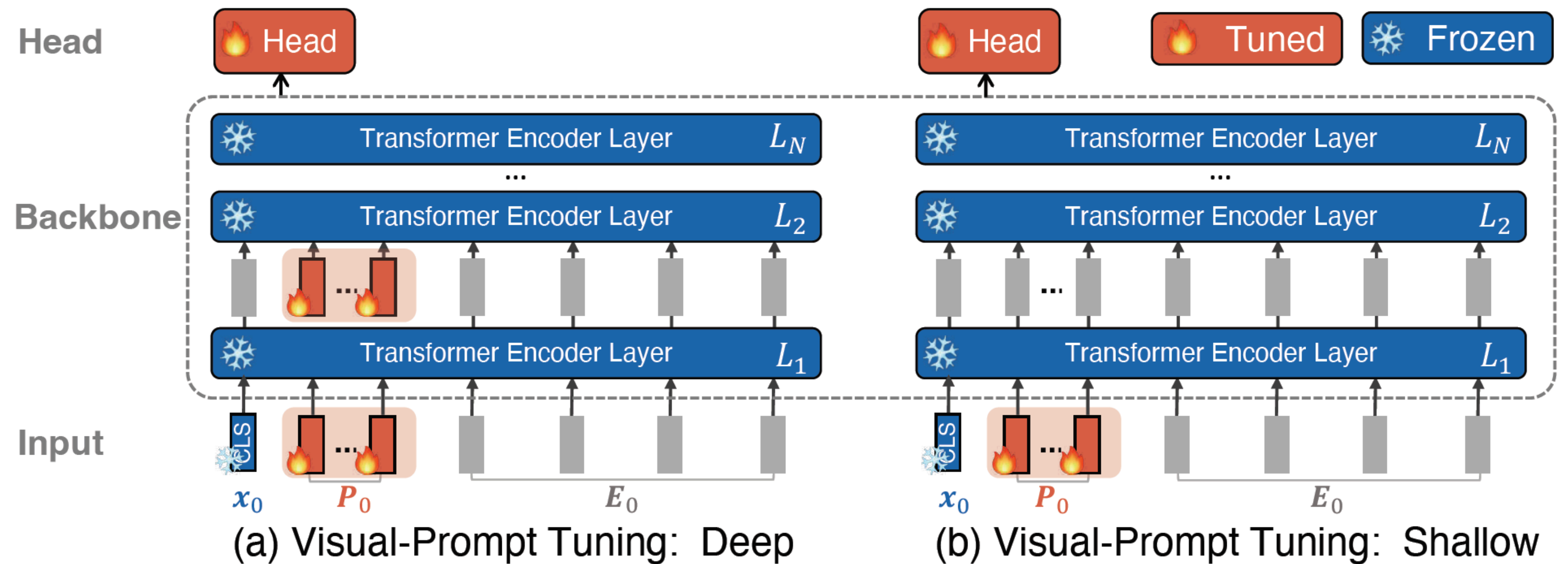
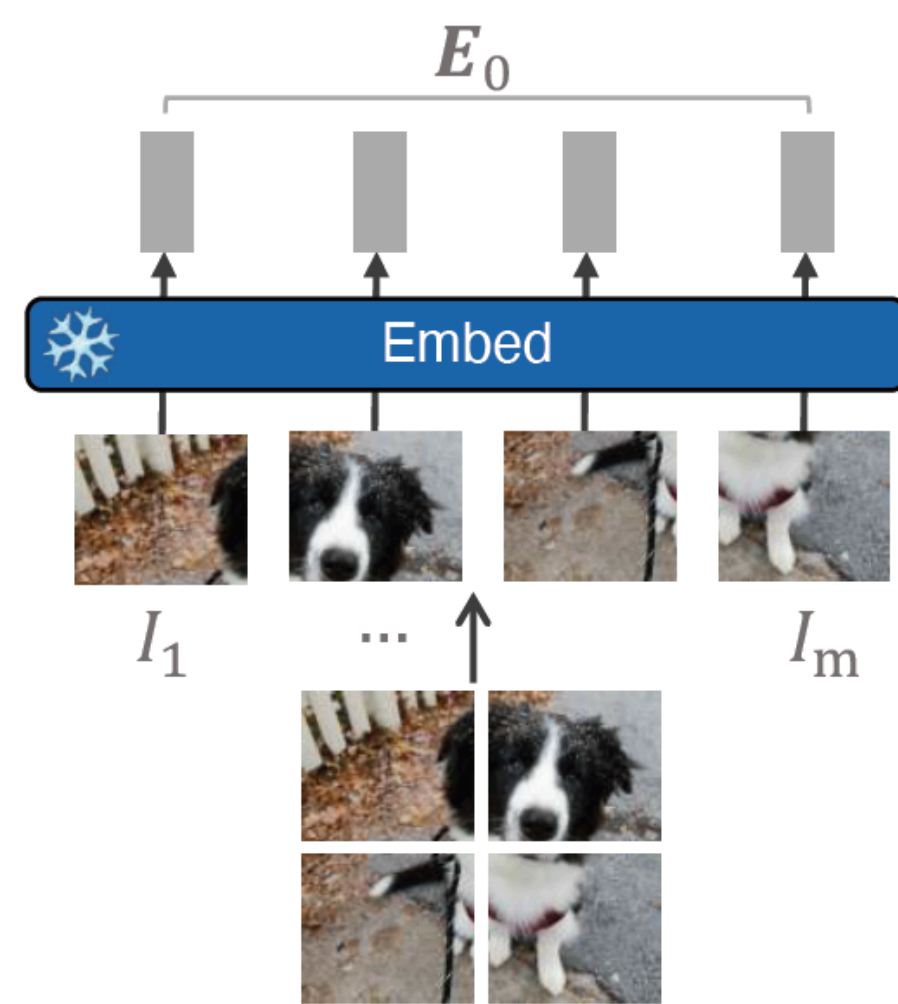


Prompt Learning in Pixel Space

Effective for reducing the distribution gap



Prompt Learning in Embedding Space



Prompt Learning in Embedding Space

	ViT-B/16 (85.8M)	Total params	Scope Input Backbone	Extra params	FGVC	Natural	VTAB-1k Specialized	Structured
	Total # of tasks				5	7	4	8
(a)	FULL	24.02×	✓		88.54	75.88	83.36	47.64
(b)	LINEAR	1.02×			79.32 (0)	68.93 (1)	77.16 (1)	26.84 (0)
	PARTIAL-1	3.00×			82.63 (0)	69.44 (2)	78.53 (0)	34.17 (0)
	MLP-3	1.35×		✓	79.80 (0)	67.80 (2)	72.83 (0)	30.62 (0)
(c)	SIDETUNE	3.69×	✓	✓	78.35 (0)	58.21 (0)	68.12 (0)	23.41 (0)
	BIAS	1.05×	✓		88.41 (3)	73.30 (3)	78.25 (0)	44.09 (2)
	ADAPTER	1.23×	✓	✓	85.66 (2)	70.39 (4)	77.11 (0)	33.43 (0)
(ours)	VPT-SHALLOW	1.04×		✓	84.62 (1)	76.81 (4)	79.66 (0)	46.98 (4)
	VPT-DEEP	1.18×	✓	✓	89.11 (4)	78.48 (6)	82.43 (2)	54.98 (8)

Outperforms full fine-tuning!

Prompt Learning in Embedding Space

	Swin-B (86.7M)	Total params	Natural	VTAB-1k	
				Specialized	Structured
	Total # of tasks		7	4	8
(a)	FULL	19.01×	79.10	86.21	59.65
(b)	LINEAR	1.01×	73.52 (5)	80.77 (0)	33.52 (0)
	MLP-3	1.47×	73.56 (5)	75.21 (0)	35.69 (0)
	PARTIAL	3.77×	73.11 (4)	81.70 (0)	34.96 (0)
(c)	BIAS	1.06×	74.19 (2)	80.14 (0)	42.42 (0)
(ours)	VPT-SHALLOW	1.01×	79.85 (6)	82.45 (0)	37.75 (0)
	VPT-DEEP	1.05×	76.78 (6)	84.53 (0)	53.35 (0)

Takeaway Message

- Visual prompting allows adaptation of foundation models in *input space*
 - This is important because input space is a universal interface for both humans and models!
- Allowing multiple types of visual prompts increases the usability of the model for *flexible integration* (e.g. Segment Anything)
 - Promptability is an open challenge!
- Learning a visual prompt can be treated as parameter-efficient fine-tuning (PEFT) and sometimes outperform full fine-tuning